## **PH101: PHYSICS1**

#### Lecture 4

## Harmonic approximation of potential energy



Potential energy for atom and many other practical systems are close to harmonic around equilibrium point but deviates at larger distance from equilibrium

Exact potential is hard to solve.

## **Harmonic approximation**

**Taylor series/expansion** 

$$V(x) = V(x_0) + V'(x_0)(x - x_0) + \frac{1}{2!}V''(x_0)(x - x_0)^2 + O(3)$$

Here  $V'(\mathbf{x}) = \frac{dV}{dx}$  and  $V''(\mathbf{x}) = \frac{d^2V}{dx^2}$ 

Here we are taking the expansion around the equilibrium distance x<sub>0</sub>.
 Hence V'(x<sub>0</sub>) =0 since the force is zero (potential has an extremum).

□ Let us assume that  $V(x_0)=0$ , the potential at the equilibrium (reference ) is zero.



#### **Taylor series/expansion Examples:**

$$e^{x} = 1 + x + \frac{x^{2}}{2!} + \frac{x^{3}}{3!} + \frac{x^{4}}{4!} + \dots$$
  

$$\sin x = x - \frac{x^{3}}{3!} + \frac{x^{5}}{5!} - \frac{x^{7}}{7!} + \dots$$
  

$$\cos x = 1 - \frac{x^{2}}{2!} + \frac{x^{4}}{4!} - \frac{x^{6}}{6!} + \dots$$
  

$$\ln(1+x) = x - \frac{x^{2}}{2} + \frac{x^{3}}{3} - \frac{x^{4}}{4} + \dots \quad for |x| < 1$$

#### Harmonic approximation continue..



frequency of vibration  $\omega =$ 

Where, Reduced mass( $\mu$ ) of oscillitator

$$\mu = \frac{m_1 m_2}{m_1 + m_2}$$

#### **Harmonic approximation: Example**



To break the molecule one has to supply energy D. This is a convenient model for diatomic molecules.

#### **Harmonic approximation: Morse Potential**

First find the equilibrium  $V'(x) = 2D\alpha (1 - e^{-\alpha (x - x_0)}) e^{-\alpha (x - x_0)} = 0$ Solving, at equilibrium  $x = x_0$ Now  $V''(x) = 2D\alpha (-\alpha e^{-\alpha (x-x_0)} + 2\alpha e^{-2\alpha (x-x_0)})$ At equilibrium  $V''(x_0) = 2D\alpha^2 \approx k$  $\omega = \sqrt{\frac{k}{\mu}} = \alpha \sqrt{2D/\mu}$ 

### Work and potential energy in 3D

**1D motion**: Displacement and force are along the same line Work done by force dW = F dx = -dVThus,  $F = -\frac{dV}{dx}$ 

$$\overrightarrow{F} \longrightarrow d\vec{r} = dx \,\hat{x}$$

**3D motion**: Displacement and force are  
in different directions  
$$dW = F \cos \theta \, dr$$
$$dW = \vec{F} \cdot d\vec{r} = F_x dx + F_y dy + F_z dz$$
$$= -dV$$
$$\vec{F} = ?$$

$$dV = -\vec{F} \cdot d\vec{r} = -(F_x dx + F_y dy + F_z dz)$$

## dV in 2D and 3D?



Total change in potential energy due to change of x by dx and y by dy  $dV = \frac{\partial V}{\partial x} dx + \frac{\partial V}{\partial y} dy$ 3D: Since, V(x, y, z)

$$dV = \frac{\partial V}{\partial x}dx + \frac{\partial V}{\partial y}dy + \frac{\partial V}{\partial z}dz$$

### **Potential energy in 3D**

We can write

$$dV = \frac{\partial V}{\partial x}dx + \frac{\partial V}{\partial y}dy + \frac{\partial V}{\partial z}dz$$
$$= \left(\frac{\partial V}{\partial x}\hat{x} + \frac{\partial V}{\partial y}\hat{y} + \frac{\partial V}{\partial z}\hat{z}\right) \cdot (\hat{x}dx + \hat{y}dy + \hat{z}dz)$$
$$dV = \left(\frac{\partial}{\partial x}\hat{x} + \frac{\partial}{\partial y}\hat{y} + \frac{\partial}{\partial z}\hat{z}\right)V \cdot (\hat{x}dx + \hat{y}dy + \hat{z}dz)$$
$$dV = \overrightarrow{\nabla}V \cdot d\overrightarrow{r}$$

 $\vec{\nabla}$  symbols stands for an operator  $\vec{\nabla} = \frac{\partial}{\partial x}\hat{x} + \frac{\partial}{\partial y}\hat{y} + \frac{\partial}{\partial z}\hat{z}$  $\vec{\nabla}V$  -this operation is know as gradient of V

Since,  

$$dV = -\vec{F} \cdot d\vec{r}$$

$$\vec{F} = -\vec{\nabla}V$$

$$F_{x} = -\frac{\partial V}{\partial x} \qquad F_{y} = -\frac{\partial V}{\partial y} \qquad F_{z} = -\frac{\partial V}{\partial z}$$

# **Gradient in plane polar!**

Let we have, 
$$V(r, \theta)$$
  
 $dV = \frac{\partial V}{\partial r} dr + \frac{\partial V}{\partial \theta} d\theta$  (by rule!)  
But,  $dV = -\vec{F} \cdot d\vec{r} = -(F_r \hat{r} + F_{\theta} \hat{\theta}) \cdot (dr \,\hat{r} + r d\theta \,\hat{\theta})$   
 $= -(F_r dr + F_{\theta} r d\theta)$   
 $F_r = -\frac{\partial V}{\partial r}$  &  $F_{\theta} = -\frac{1}{r} \frac{\partial V}{\partial \theta}$   
Or,  $dV = \vec{\nabla} V \cdot d\vec{r} = -(F_r \hat{r} + F_{\theta} \hat{\theta})$   
 $\Rightarrow \quad \vec{\nabla} = \frac{\partial (\cdot)}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial (\cdot)}{\partial \theta} \hat{\theta}$  (in plane polar)

#### **Note: Conservative vs non-conservative forces**

 $\vec{F} = -\vec{\nabla}V$  (true only for conservative forces ?)

#### Let's review how we have arrived to this relation:

We have assumed that Work done by the force is entirely stored in the system as potential energy, -dW = dV

Work done by all type of forces do not converted to potential energy stored in the system, it may lost by dissipation in the form of heat, sound etc. Those forces are dissipative force/non-conservative force, **Example: Friction** 

Work done by dissipative force  $dW = \vec{f} \cdot d\vec{r} \neq dV$ , Energy is not stored as potential energy. Hence  $\vec{f} \neq -\vec{\nabla}V$   $T + V \neq constant$  when a particle is under dissipative forces. Thus they are nonconservative force.

#### **Note: Conservative force**

B

A

Is the force always derivable from scalar potential  $\vec{F} = -\vec{\nabla}V$ ? Answer is no, all forces are not derivable from scalar potential.

Those forces which are derivable from scalar potential ( $\vec{F} = -\vec{\nabla}V$ ) are known as **conservative force**.

Work done due to motion from A to B

$$dW = \vec{F} \cdot d\vec{r} = -\vec{\nabla}V \cdot d\vec{r} = -dV ; thus W = -\int_{A} dV = V_A - V_B$$

Agian, 
$$dW = \vec{F} \cdot d\vec{r} = m \frac{d\vec{v}}{dt} \cdot d\vec{r} = m \frac{d\vec{v}}{dt} \cdot \vec{v} dt = \frac{1}{2} m d(\vec{v} \cdot \vec{v}) = \frac{1}{2} m d(v^2)$$
  
$$W = \int_{A}^{B} \frac{1}{2} m d(v^2) = \frac{1}{2} m v_B^2 - \frac{1}{2} m v_A^2 (= Change in K.E.)$$

В

Thus,  $V_A - V_B = \frac{1}{2} m v_B^2 - \frac{1}{2} m v_A^2 \implies V_A + \frac{1}{2} m v_A^2 = V_B + \frac{1}{2} m v_B^2$ 

**Energy conserved (True for conservative force )** 

## **Conservative forces**

For a conservative force 
$$\vec{F} = -\vec{\nabla}V$$
, where  $\vec{\nabla} = \frac{\partial}{\partial x}\hat{x} + \frac{\partial}{\partial y}\hat{y} + \frac{\partial}{\partial z}\hat{z}$   
For a conservative force what will be the value of  $\vec{\nabla} \times \vec{F}$ ?  
Let's remember that:  $\vec{A} \times \vec{B} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ A_x & A_y & A_z \\ B_x & B_y & F_z \end{vmatrix}$   
**□ "Curl"** of a vector in Cartesian  
 $\vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix} = \hat{x} \left( \frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z} \right) + \hat{y} \left( \frac{\partial F_x}{\partial z} - \frac{\partial F_z}{\partial x} \right) + \hat{z} \left( \frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \right)$   
 $\frac{\partial F_z}{\partial y} = \frac{\partial(-\frac{\partial V}{\partial z})}{\partial y} = -\frac{\partial^2 V}{\partial y \partial z} & \frac{\partial F_y}{\partial z} = \frac{\partial(-\frac{\partial V}{\partial y})}{\partial z} = -\frac{\partial^2 V}{\partial z \partial y}$  But,  $\frac{\partial^2 V}{\partial x \partial y} = \frac{\partial^2 V}{\partial y \partial x}$   
*(order is immeterial by rule!)*

For a conservative force:  $\vec{\nabla} \times \vec{F} = 0$ 

#### Summery

**Taylor series expansion of a potential in 1D** 

$$V(x) = V(x_0) + V'(x_0)(x - x_0) + \frac{1}{2!}V''(x_0)(x - x_0)^2 + O(3)$$
  
Here  $V'(x) = \frac{dU}{dx}$  and  $V''(x) = \frac{d^2V}{dx^2}$   
Harmonic approximation consider only upto square term  
Frequency of oscillation  $\omega = \sqrt{\frac{k}{\mu}}$ ,  $k = U''(x_0)$ , and  $\mu$  is the reduced mass.

So, if

$$\vec{F} = -\vec{\nabla}V$$
 ("gradient" of V)

"Curl" of F,  $\overrightarrow{\nabla} \times \overrightarrow{F} = 0$  (always!)

Curl of gradient is always  $\operatorname{zero}(\overrightarrow{\nabla} \times \overrightarrow{\nabla} f = 0)$  (for any scalar function)

