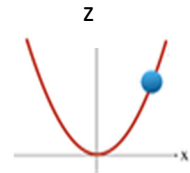
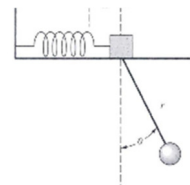


- I. For the following systems (a) obtain the constraint relations, (b) determine the degrees of freedom (DOF), (c) setup the Lagrangian in terms of generalized coordinates, and (d) obtain the Euler-Lagrange (E-L) equation of motion. Ignore frictional forces, unless otherwise mentioned! Always, make a sketch of the system, marking the origin as O, (w.r.to which the potential energy is defined), the Cartesian axes and the choice of generalized coordinates chosen.

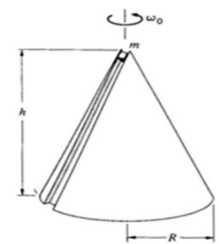
1. A bead of mass, m , sliding on a parabolic wire (kept vertical), $z = \alpha x^2$ under gravity.



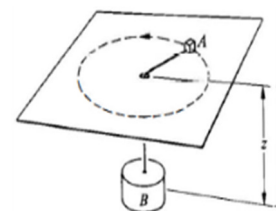
2. A mass M is confined to move on the x -axis under action of a spring of spring-constant, k , and equilibrium length, l . A small mass, m hanging from M is free to oscillate on the vertical plane under gravity.



3. A solid cone of height h and radius R is free to rotate about the vertical z -axis. At time $t=0$ small mass m starts sliding down from the apex of the cone along a straight groove cut on its surface, under gravity. Let the moment of inertia of the cone about the z -axis is I . If at time, $t=0$, the angular velocity of the cone is ω_0 , find the angular velocity of the cone when the mass m leaves it. Also, show that the angular momentum of the system along the z -axis is conserved.



4. A particle of mass M (marked A) is confined to move the horizontal x - y plane. Another mass m (marked B) which is free to move on the vertical z -axis is tied to the mass A through a light string of length l .



[Homework to students]

- II. Formulate the Lagrangian for the following systems.
- A projectile of mass, m , moving on the vertical xy – plane under gravity. (Obtain L in terms of both Cartesian and plane polar coordinates. Which of the two is *more insightful* in this case?!)
 - A bead of mass, m , moving on parabolic wire, given by, $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$, where a and b are the semi-major and semi-minor axes, respectively. (Ignore gravity)
 - A point mass m constrained to move on the surface of a fixed gravitating solid sphere of mass M and radius R .