

# FDTD: An Introduction

$$\frac{\partial H_x}{\partial t} = -\frac{1}{\mu_0} \left( \frac{\partial E_z}{\partial y} - \frac{\partial E_y}{\partial z} \right)$$

$$\frac{H_x^{n+1/2}(p, q+1/2, r+1/2) - H_x^{n-1/2}(p, q+1/2, r+1/2)}{\Delta t} =$$
$$\frac{1}{\mu_0} \left[ \frac{E_y^n(p, q+1/2, r+1) - E_y^n(p, q+1/2, r)}{\Delta z} \right]$$
$$- \frac{1}{\mu_0} \left[ \frac{E_z^n(p, q+1, r+1/2) - E_z^n(p, q, r+1/2)}{\Delta y} \right]$$

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$$\frac{\partial H_y}{\partial t} = -\frac{1}{\mu_0} \left( \frac{\partial E_x}{\partial z} - \frac{\partial E_z}{\partial x} \right)$$

$$\frac{H_y^{n+1/2}(p+1/2, q, r+1/2) - H_y^{n-1/2}(p+1/2, q, r+1/2)}{\Delta t} =$$
$$\frac{1}{\mu_0} \left[ \frac{E_z^n(p+1, q, r+1/2) - E_z^n(p, q, r+1/2)}{\Delta x} \right]$$
$$- \frac{1}{\mu_0} \left[ \frac{E_x^n(p+1/2, q, r+1) - E_x^n(p+1/2, q, r)}{\Delta z} \right]$$

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$$\frac{\partial H_z}{\partial t} = -\frac{1}{\mu_0} \left( \frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} \right)$$

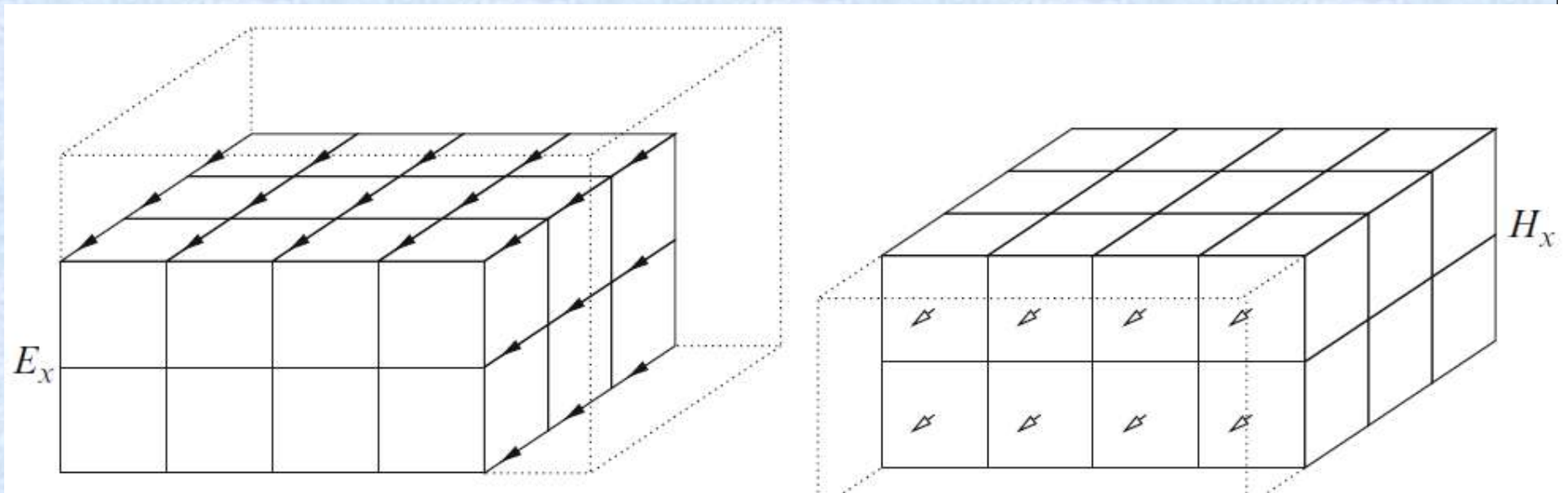
$$\frac{H_z^{n+1/2}(p+1/2, q+1/2, r) - H_z^{n-1/2}(p+1/2, q+1/2, r)}{\Delta t} =$$
$$\frac{1}{\mu_0} \left[ \frac{E_x^n(p+1/2, q+1/2, r) - E_x^n(p+1/2, q, r)}{\Delta y} \right]$$
$$- \frac{1}{\mu_0} \left[ \frac{E_y^n(p+1, q+1/2, r) - E_y^n(p, q+1/2, r)}{\Delta x} \right]$$

# FDTD: An Introduction

- *FDTD simulation of cubical cavity (fDTD\_3D\_demo.m)*
- We will use FDTD to find
  - the resonant frequencies of an air-filled cubical cavity with metal walls
- Peaks in the frequency response indicate
  - the presence of resonant modes in the cavity
- An initial Hz field excites only
  - the TE modes
- The first four eigenfrequencies
  - $TE_{101}$ ,  $TE_{011}/TE_{201}$ ,  $TE_{111}$  and  $TE_{102}$  modes

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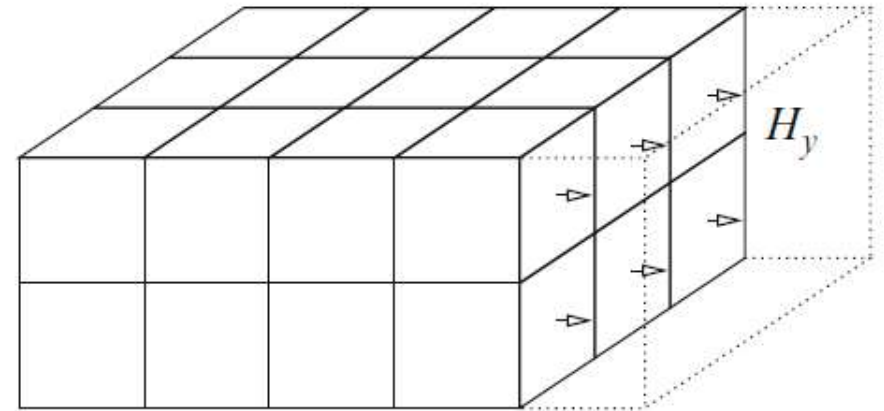
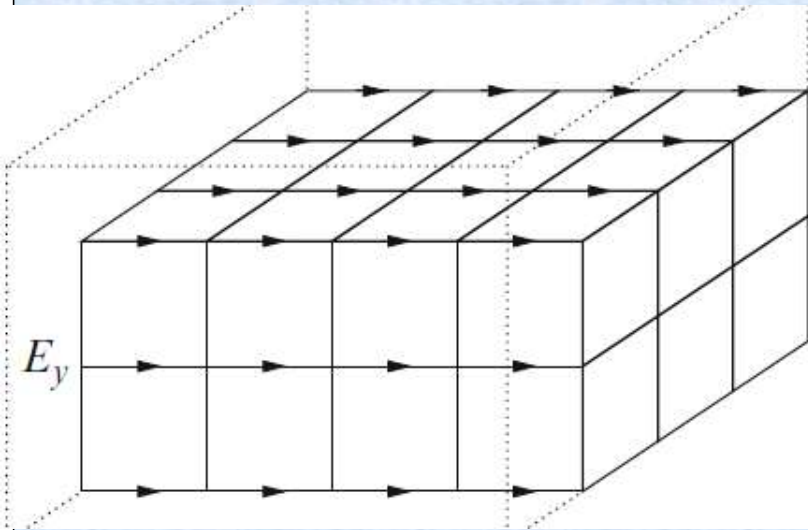
- Field components placed on a grid with  $3 \times 4 \times 2$  cells



- For  $E_x$  ( $3 \times 5 \times 3$ ) and  $H_x$  ( $4 \times 4 \times 2$ )

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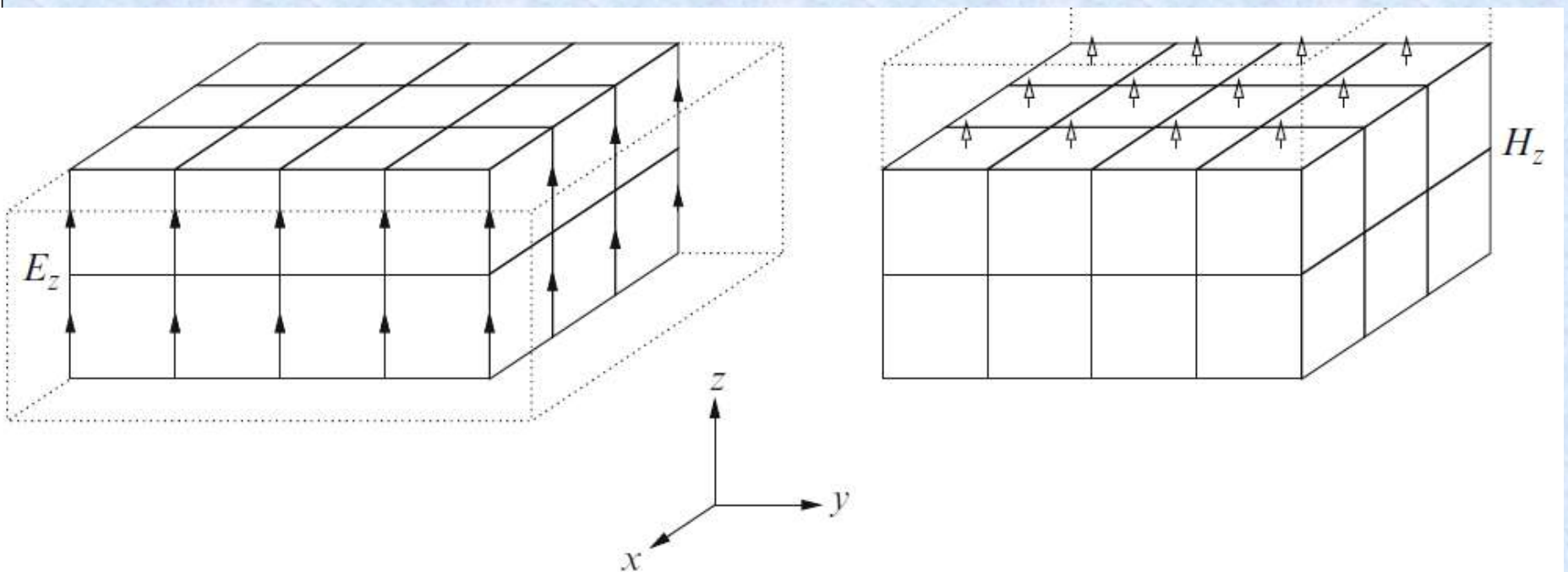
- Field components placed on a grid with  $3 \times 4 \times 2$  cells



- For  $E_y$  ( $4 \times 4 \times 3$ ) and  $H_y$  ( $3 \times 5 \times 2$ )

# FDTD: An Introduction

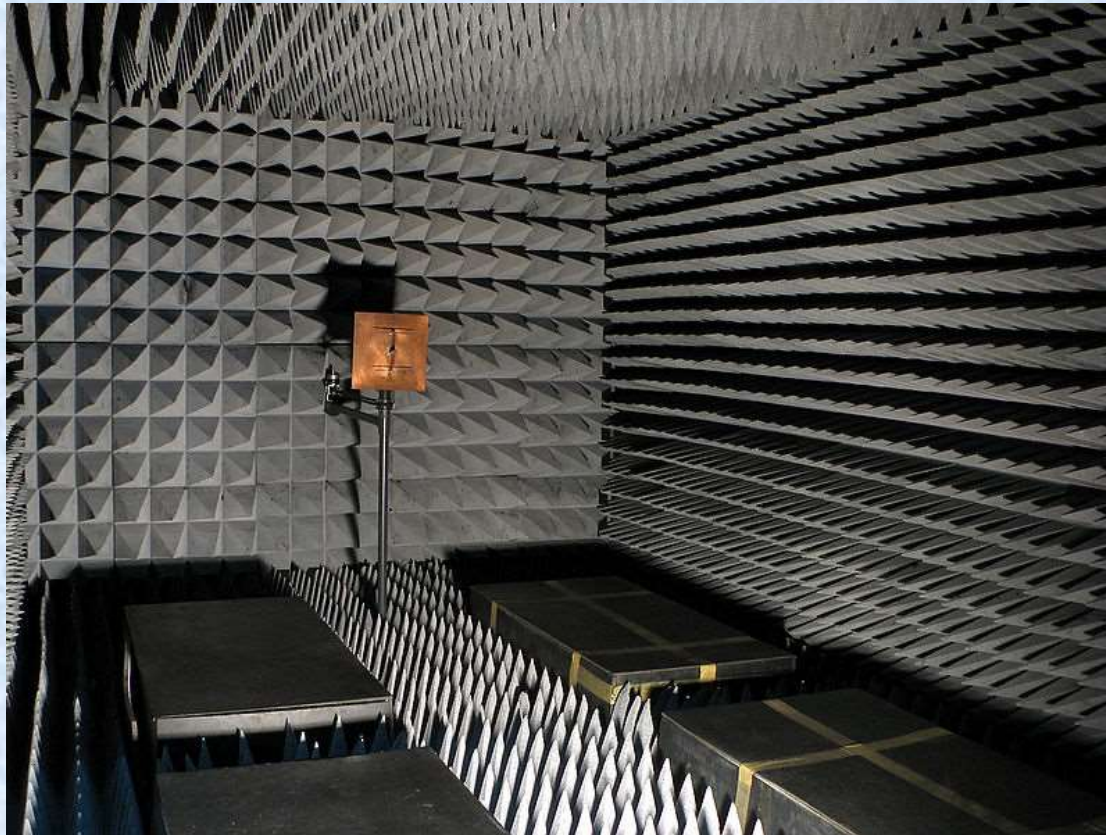
- Field components placed on a grid with  $3 \times 4 \times 2$  cells



- For  $E_z$  ( $4 \times 5 \times 2$ ) and  $H_z$  ( $3 \times 4 \times 3$ )

# FDTD: An Introduction

- Artificial absorbers on the walls of anechoic chamber





# FDTD: An Introduction

## 4. Perfectly Matched Layers

- Berenger's PML is an artificial material
- that is theoretically designed to create no reflections regardless of the
  - frequency,
  - polarization and
  - angle of incidence of a plane wave upon its interface

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- PML could be analyzed in stretched coordinate systems
- Source-free Maxwell's equations

$$\nabla_{stretched} \times \vec{E} = -j\omega\mu\vec{H}; \nabla_{stretched} \times \vec{H} = j\omega\varepsilon\vec{E};$$

$$\nabla_{stretched} \cdot (\varepsilon\vec{E}) = 0; \nabla_{stretched} \cdot (\mu\vec{H}) = 0;$$

$$\nabla_{stretched} = \hat{x} \frac{1}{s_x(x)} \frac{\partial}{\partial x} + \hat{y} \frac{1}{s_y(y)} \frac{\partial}{\partial y} + \hat{z} \frac{1}{s_z(z)} \frac{\partial}{\partial z}$$

- Consider plane waves

$$\vec{E} = \vec{E}_0 e^{-j\vec{k} \cdot \vec{r}}; \vec{H} = \vec{H}_0 e^{-j\vec{k} \cdot \vec{r}}$$

$$\vec{k} \cdot \vec{r} = k_x x + k_y y + k_z z$$

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- Substituting these into Maxwell's equations, we have,

$$\vec{k}_{stretched} \times \vec{E} = \omega \mu \vec{H}; \vec{k}_{stretched} \times \vec{H} = -\epsilon \vec{E};$$

$$\vec{k}_{stretched} \bullet (\epsilon \vec{E}) = 0; \vec{k}_{stretched} \bullet (\mu \vec{H}) = 0;$$

$$\vec{k}_{stretched} = \hat{x} \frac{k_x}{s_x} + \hat{y} \frac{k_y}{s_y} + \hat{z} \frac{k_z}{s_z}$$

$$\vec{k}_{stretched} \bullet \vec{k}_{stretched} = \left( \frac{k_x}{s_x} \right)^2 + \left( \frac{k_y}{s_y} \right)^2 + \left( \frac{k_z}{s_y} \right)^2 = k^2$$

- Solution to the above equation is given by

$$k_x = k s_x \sin \theta \cos \phi, k_y = k s_y \sin \theta \sin \phi, k_z = k s_z \cos \theta$$

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- If  $s_x$  is a **complex number with a negative imaginary part**,
  - the wave will be attenuated in the x direction

$$e^{-jk_x x} = e^{-jks_x \sin \theta \cos \phi x} = e^{-jk(s' - js'') \sin \theta \cos \phi x}, s' \geq 1, s'' > 0$$

- Wave impedance is independent of coordinate stretching

$$\eta = \frac{|\vec{E}|}{|\vec{H}|} = \frac{\omega \mu}{|\vec{k}_{stretched}|} = \frac{\omega \mu}{|\vec{k}|} = \sqrt{\frac{\mu}{\epsilon}}$$

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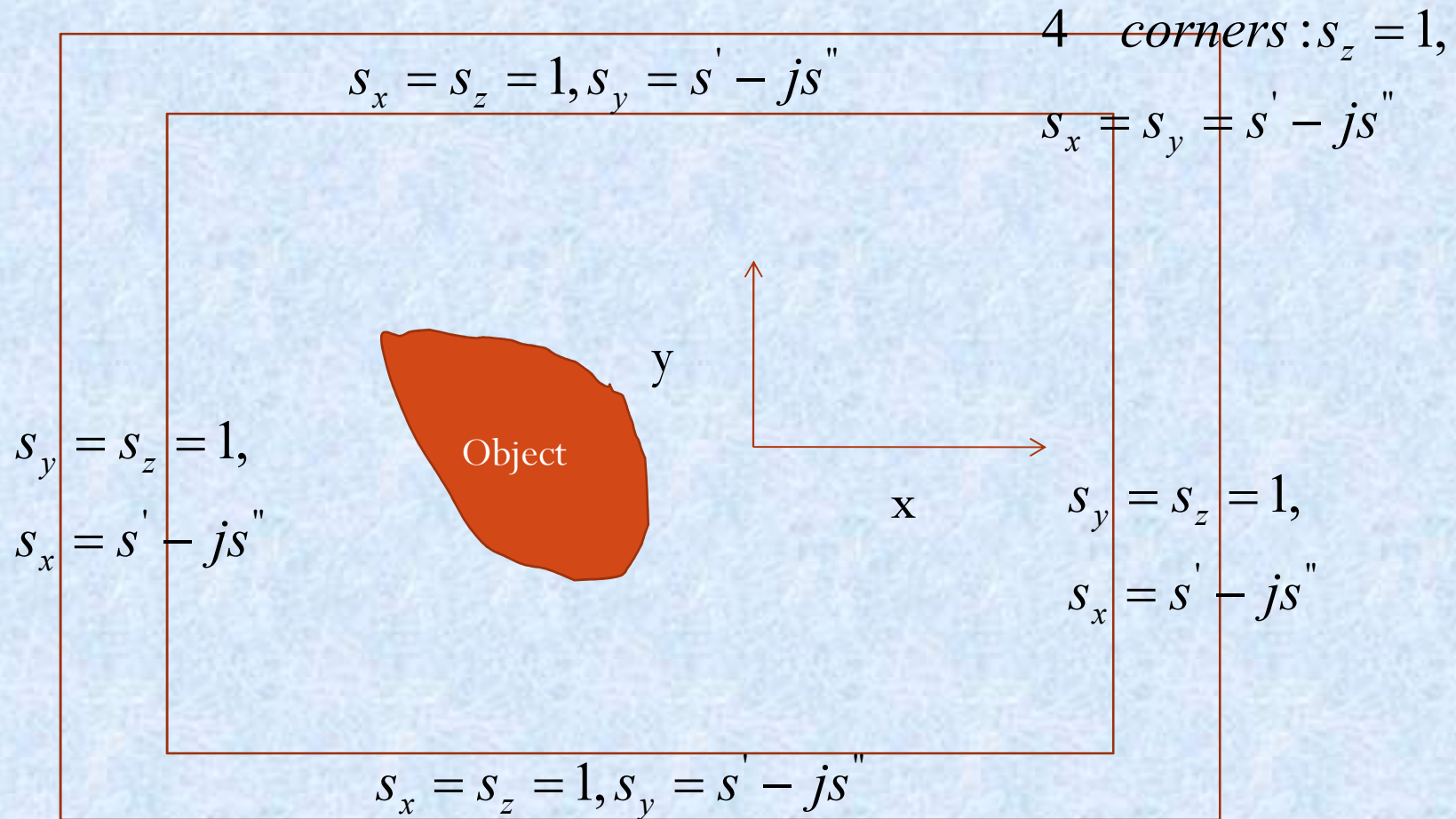


Fig. 5 Computational domain truncated using the conductor backed PMLs

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$$\begin{aligned}\nabla_{stretched} \times \vec{E} \\ &= \frac{1}{s_x} \frac{\partial}{\partial x} (\hat{x} \times \vec{E}) + \frac{1}{s_y} \frac{\partial}{\partial y} (\hat{y} \times \vec{E}) + \frac{1}{s_z} \frac{\partial}{\partial z} (\hat{z} \times \vec{E}) \\ &= -j\omega\mu\vec{H}\end{aligned}$$

LHS has three terms, we can split the magnetic field into three parts

# FDTD: An Introduction

Splitting the magnetic field and equating LHS and RHS

$$\vec{H} = \vec{H}_{sx} + \vec{H}_{sy} + \vec{H}_{sz}$$

$$\frac{1}{s_x} \frac{\partial}{\partial x} (\hat{x} \times \vec{E}) = -j\omega\mu\vec{H}_{sx}$$

$$\frac{1}{s_y} \frac{\partial}{\partial y} (\hat{y} \times \vec{E}) = -j\omega\mu\vec{H}_{sy}$$

$$\frac{1}{s_z} \frac{\partial}{\partial z} (\hat{z} \times \vec{E}) = -j\omega\mu\vec{H}_{sz}$$

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$$\text{Choosing } s_x = 1 - j \frac{\sigma_x}{\omega \epsilon}, s_y = 1 - j \frac{\sigma_y}{\omega \epsilon}, s_z = 1 - j \frac{\sigma_z}{\omega \epsilon}$$

$$\frac{\partial}{\partial x} (\hat{x} \times \vec{E}) = -j\omega\mu \left(1 - j \frac{\sigma_x}{\omega \epsilon}\right) \vec{H}_{sx} = -\mu \frac{\partial \vec{H}_{sx}}{\partial t} - \frac{\sigma_x \mu}{\epsilon} \vec{H}_{sx}$$

$$\frac{\partial}{\partial y} (\hat{y} \times \vec{E}) = -j\omega\mu s_y \vec{H}_{sy} = -\mu \frac{\partial \vec{H}_{sy}}{\partial t} - \frac{\sigma_y \mu}{\epsilon} \vec{H}_{sy}$$

$$\frac{\partial}{\partial z} (\hat{z} \times \vec{E}) = -j\omega\mu s_z \vec{H}_{sz} = -\mu \frac{\partial \vec{H}_{sz}}{\partial t} - \frac{\sigma_z \mu}{\epsilon} \vec{H}_{sz}$$

May be used for update equations for magnetic fields



# FDTD: An Introduction

Similarly, Splitting the electric field

$$\nabla_{stretched} \times \vec{H} = j\omega\epsilon\vec{E}; \quad \vec{E} = \vec{E}_{sx} + \vec{E}_{sy} + \vec{E}_{sz}$$

$$\frac{\partial}{\partial x} (\hat{x} \times \vec{H}) = \epsilon \frac{\partial \vec{E}_{sx}}{\partial t} + \sigma_x \vec{E}_{sx}$$

$$\frac{\partial}{\partial y} (\hat{y} \times \vec{H}) = \epsilon \frac{\partial \vec{E}_{sy}}{\partial t} + \sigma_y \vec{E}_{sy}$$

$$\frac{\partial}{\partial z} (\hat{z} \times \vec{H}) = \epsilon \frac{\partial \vec{E}_{sz}}{\partial t} + \sigma_z \vec{E}_{sz}$$

May be used for update equations for electric fields

# FDTD: An Introduction

- For instance, consider 2-D TM<sup>z</sup> problem
- $E_x = 0, E_y = 0, H_z = 0, \frac{\partial}{\partial z} = 0$

$$\vec{E} = E_z \hat{z}; \vec{H} = H_x \hat{x} + H_y \hat{y}$$

$\hat{x} \times \vec{E}$  will be along  $\hat{y}$  direction

- Hence,  $\vec{H}_{sx} = \hat{y} H_y$
- Similarly,

$$\vec{H}_{sy} = \hat{x} H_x, \vec{H}_{sz} = 0$$

$$\frac{1}{s_x} \frac{\partial}{\partial x} (\hat{x} \times \vec{E}) = -j\omega\mu \vec{H}_{sx}$$

$$\frac{1}{s_y} \frac{\partial}{\partial y} (\hat{y} \times \vec{E}) = -j\omega\mu \vec{H}_{sy}$$

$$\frac{1}{s_z} \frac{\partial}{\partial z} (\hat{z} \times \vec{E}) = -j\omega\mu \vec{H}_{sz}$$

# FDTD: An Introduction

$$\begin{aligned}\frac{\partial}{\partial x}(\hat{x} \times \vec{E}) &= \frac{\partial}{\partial x}(\hat{x} \times E_z \hat{z}) = -\frac{\partial E_z}{\partial x} \hat{y} \\ &= -j\omega\mu s_x \vec{H}_{sx} = -j\omega\mu s_y H_y \hat{y} = \left( -\mu \frac{\partial H_y}{\partial t} - \frac{\sigma_x \mu}{\epsilon} H_y \right) \hat{y}\end{aligned}$$

$$\begin{aligned}\frac{\partial}{\partial y}(\hat{y} \times \vec{E}) &= \frac{\partial}{\partial y}(\hat{y} \times E_z \hat{z}) = \frac{\partial E_z}{\partial y} \hat{x} \\ &= -j\omega\mu s_y \vec{H}_{sy} = -j\omega\mu s_y H_x \hat{x} = \left( -\mu \frac{\partial H_x}{\partial t} - \frac{\sigma_y \mu}{\epsilon} H_x \right) \hat{x}\end{aligned}$$

$$\frac{\partial}{\partial z}(\hat{z} \times \vec{E}) = -j\omega\mu s_z \vec{H}_{sz} = 0$$

# FDTD: An Introduction

- Split field for magnetic fields for 2-D TM<sup>z</sup> problem

$$\begin{aligned}\epsilon \frac{\partial E_z}{\partial x} &= \mu \epsilon \frac{\partial H_y}{\partial t} + \sigma_x \mu H_y \\ \epsilon \frac{\partial E_z}{\partial y} &= -\mu \epsilon \frac{\partial H_x}{\partial t} - \sigma_y \mu H_x\end{aligned}$$

- Split fields for electric fields (TM<sup>z</sup>, electric field has only z components)

$\hat{x} \times \vec{H}, \hat{y} \times \vec{H}$  will be along  $\hat{z}$  direction

$$\therefore \vec{E} = E_z \hat{z}; \vec{H} = H_x \hat{x} + H_y \hat{y}$$

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$$\frac{\partial}{\partial x}(\hat{x} \times \vec{H}) = \frac{\partial H_y}{\partial x} \hat{z} = \epsilon \frac{\partial \vec{E}_{sx}}{\partial t} + \sigma_x \vec{E}_{sx} = \left( \epsilon \frac{\partial \vec{E}_{sx,z}}{\partial t} + \sigma_x \vec{E}_{sx,z} \right) \hat{z}$$

$$\frac{\partial}{\partial y}(\hat{y} \times \vec{H}) = -\frac{\partial H_x}{\partial y} \hat{z} = \epsilon \frac{\partial \vec{E}_{sy}}{\partial t} + \sigma_y \vec{E}_{sy} = \left( \epsilon \frac{\partial \vec{E}_{sy,z}}{\partial t} + \sigma_y \vec{E}_{sy,z} \right) \hat{z}$$

$$\frac{\partial}{\partial z}(\hat{z} \times \vec{H}) = \epsilon \frac{\partial \vec{E}_{sz}}{\partial t} + \sigma_z \vec{E}_{sz} = 0$$

$$\therefore \vec{E} = E_z \hat{z}; \vec{H} = H_x \hat{x} + H_y \hat{y}$$

# FDTD: An Introduction

- Hence, Split field for electric fields for 2-D TM<sup>z</sup> problem

$$\frac{\partial H_y}{\partial x} = \epsilon \frac{\partial E_{sx,z}}{\partial t} + \sigma_x E_{sx,z}$$
$$\frac{\partial H_x}{\partial y} = -\epsilon \frac{\partial E_{sy,z}}{\partial t} - \sigma_y E_{sy,z}$$

$$E_z = E_{sx,z} + E_{sy,z}$$