- Finite element analysis of vector fields
- FEM can be extended to deal BVP involving vector fields
- It is very important for electrodynamic problems
 - which deal with vector electromagnetic fields
- BVP:
- ullet Consider the problem of finding the electric field intensity $ec{E}$
 - ullet due to impressed electric current density $ec{J}_{imp}$ in a domain Ω
 - ullet characterized by permittivity $oldsymbol{arepsilon}$ and permeability μ
- ullet To calculate $ec{E}$ we need to solve Maxwell's equations

$$\bullet \nabla \times \vec{E} = -j\omega\mu \vec{H} \tag{1}$$

•
$$\nabla \times \vec{H} = j\omega \epsilon \vec{E} + \vec{J}_{imp}$$
 (2)

•
$$\nabla \cdot (\epsilon \vec{E}) = -\frac{1}{j\omega} \nabla \cdot \vec{J}_{imp}$$
 $: \nabla \cdot \vec{J} = -\frac{\partial \rho_v}{\partial t} = -j\omega \rho_v$

- $\bullet \nabla \cdot \left(\mu \vec{H}\right) = 0$
 - subject to certain BCs
- In first equation divide by μ_r we have

$$\bullet \left(\frac{1}{\mu_r} \nabla \times \vec{E} \right) = -j\omega \mu_0 \vec{H}$$

Taking another curl

•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) = -j\omega \mu_0 (\nabla \times \vec{H})$$

Putting second equation

•
$$\nabla \times \vec{H} = j\omega \epsilon \vec{E} + \vec{J}_{imp}$$

in

•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) = -j\omega \mu_0 (\nabla \times \vec{H})$$

• we have

•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) = -j\omega \mu_0 (j\omega \epsilon \vec{E} + \vec{J}_{imp})$$

•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) = \omega^2 \mu_0 \epsilon_0 \epsilon_r \vec{E} - j\omega \mu_0 \vec{J}_{imp}$$

•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) = k_0^2 \epsilon_r \vec{E} - j\omega \mu_0 \vec{J}_{imp}$$

• where
$$k_0^2 = \omega^2 \mu_0 \epsilon_0, Z_0 = \sqrt{\frac{\mu_0}{\epsilon_0}}$$
 and

• hence
$$Z_0 k_0 = \omega \sqrt{\mu_0 \epsilon_0} \sqrt{\frac{\mu_0}{\epsilon_0}} = \omega \mu_0$$

• So

•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) - k_0^2 \epsilon_r \vec{E} = -j Z_0 k_0 \vec{J}_{imp}$$

The functional for such electrodynamic problems¹ is

•
$$F(\vec{E}) = \int_{\Omega} \left[\frac{1}{\mu_r} (\nabla \times \vec{E}) \cdot (\nabla \times \vec{E}) - k_0^2 \epsilon_r \vec{E} \cdot \vec{E} \right] d\Omega + jZ_0 k_0 \int \vec{E} \cdot \vec{J}_{imp} d\Omega$$

For source free vector wave equation

•
$$\nabla \times \left(\frac{1}{\mu_r} \nabla \times \vec{E}\right) - k_i^2 \epsilon_r \vec{E} = 0$$

The functional is

•
$$F(\vec{E}) = \int_{\Omega} \left[\frac{1}{\mu_r} (\nabla \times \vec{E}) \cdot (\nabla \times \vec{E}) - k_i^2 \epsilon_r \vec{E} \cdot \vec{E} \right] d\Omega$$

• ¹ J.-M. Jin, *The Finite Element Method in Electromagnetics*, John Wiley & Sons, 2002

- The solution is the set of eignevalues k_i and associated eigenvectors \vec{E}_i
- High frequency variational function
- The 2-D variational functional analysis for a homogeneous waveguide
 - For homogeneously filled waveguide, eigenmode splits into TE and TM modes
- The functional for the transverse field components subject to the prescribed boundary condition
 - $\hat{n} \times \vec{E}_t = 0$
- is given on next slide

- $F(\vec{E}_t) = \int \int_{S} \left[\frac{1}{\mu_r} (\nabla_t \times \vec{E}_t) \cdot (\nabla_t \times \vec{E}_t) k_0^2 \epsilon_r \vec{E}_t \cdot \vec{E}_t \right] dS$
- Considering TE modes
 - $E_z = 0$
- The vectors of unknowns $\{e\}$ in the generalized eigenvalue problem is found as
 - $[S]{e} = k^2[T]{e}$
- which will also include prescribed values also

- In order include only contribution from free edges
 - $[S_{ff}]\{e_f\} = k^2 [T_{ff}]\{e_f\}$
- which will also include prescribed nodes also
- This can be obtained from the functional

•
$$F\{e\} = \left\{e_f e_p\right\}^T \begin{bmatrix} S_{ff} & S_{fp} \\ S_{pf} & S_{pp} \end{bmatrix} \left\{e_f e_p\right\}$$

- ullet Differentiate $F\{e\}$ w.r.t. $\left\{e_f
 ight\}$
- ullet then applying the prescribed conditions $\{e_p\}=0$
- We can get the above relation
 - $[S_{ff}]\{e_f\} = k^2[T_{ff}]\{e_f\}$

Explicit formula for the elemental matrix entries

•
$$S_{ij} = \int \int_{S} (\nabla_{t} \times \vec{N}_{i}) \cdot (\nabla_{t} \times \vec{N}_{j}) dS$$

and

•
$$T_{ij} = \int \int_{S} \vec{N}_{i} \cdot \vec{N}_{j} dS$$

- For wave propagating along z-axis,
 - ∇_t and $\nabla_t \times$ are operators in the x-y plane
- The three simplex coordinates are given by

$$\bullet \ \lambda_i = a_i + b_i x + c_i y$$

• Therefore,

$$\bullet \ \lambda_1 = a_1 + b_1 x + c_1 y$$

$$\bullet \ \lambda_2 = a_2 + b_2 x + c_2 y$$

$$\bullet \ \lambda_3 = a_3 + b_3 x + c_3 y$$

• In matrix form

$$\bullet \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \end{bmatrix} = \begin{bmatrix} b_1 & c_1 & a_1 \\ b_2 & c_2 & a_2 \\ b_3 & c_3 & a_3 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

• Also we know that λ_i is equal to 1 for node i and zero for other nodes

In matrix form

$$\begin{bmatrix}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{bmatrix} = \begin{bmatrix}
b_1 & c_1 & a_1 \\
b_2 & c_2 & a_2 \\
b_3 & c_3 & a_3
\end{bmatrix} \begin{bmatrix}
x_1 & x_2 & x_3 \\
y_1 & y_2 & y_3 \\
1 & 1 & 1
\end{bmatrix}$$

• Hence we can find (b_i, c_i, a_i) as follows

$$\bullet \begin{bmatrix} b_1 & c_1 & a_1 \\ b_2 & c_2 & a_2 \\ b_3 & c_3 & a_3 \end{bmatrix} = \begin{bmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \\ 1 & 1 & 1 \end{bmatrix}^{-1}$$

• Let us define

•
$$\vec{v}_{ij} = \nabla \lambda_i \times \nabla \lambda_j = (b_i \hat{x} + c_i \hat{y}) \times (b_j \hat{x} + c_j \hat{y}) = (b_i c_j - b_j c_i) \hat{z} = -\vec{v}_{ji}$$

- Let us also define
- $\phi_{ij} = \nabla \lambda_i \cdot \nabla \lambda_j = (b_i \hat{x} + c_i \hat{y}) \cdot (b_j \hat{x} + c_j \hat{y}) = b_i b_j + c_i c_j$
- Now we can find curl of $\vec{N}_i = \vec{w}_{i1,i2} = \lambda_{i1} \nabla \lambda_{i2} \lambda_{i2} \nabla \lambda_{i1}$ where i_1 and i_2 are the endpoints of edge i as follows
- $\nabla \times \vec{N}_i = \nabla \times (\lambda_{i1} \nabla \lambda_{i2} \lambda_{i2} \nabla \lambda_{i1}) = \nabla \times (\lambda_{i1} \nabla \lambda_{i2}) \nabla \times (\lambda_{i2} \nabla \lambda_{i1})$
- Note that $\nabla \times (\phi \vec{A}) = \phi \nabla \times (\vec{A}) + \nabla \phi \times (\vec{A})$
- And since $\nabla \times (\nabla \Psi) = 0$ where Ψ is scalar function, we have,
- $\nabla \times (\lambda_{i1} \nabla \lambda_{i2}) = \nabla \lambda_{i1} \times \nabla \lambda_{i2}$ and $\nabla \times (\lambda_{i2} \nabla \lambda_{i1}) = \nabla \lambda_{i2} \times \nabla \lambda_{i1} = -\nabla \lambda_{i1} \times \nabla \lambda_{i2}$
- $\therefore \nabla \times \vec{N}_i = 2\nabla \lambda_{i1} \times \nabla \lambda_{i2} = 2\vec{v}_{i1,i2}$

Hence

•
$$S_{ij} = \int \int_{S} (\vec{v}_t \times \vec{N}_i) \cdot (\vec{v}_t \times \vec{N}_j) dS =$$

4 $\int \int_{S} (\vec{v}_{i1,i2}) \cdot (\vec{v}_{j1,j2}) dS = 4A(\vec{v}_{i1,i2}) \cdot (\vec{v}_{j1,j2})$

• where A = |A'| and A' is defined as

$$\bullet \ A' = \frac{1}{2} \begin{vmatrix} 1 & x_1 & y_1 \\ 1 & x_2 & y_2 \\ 1 & x_3 & y_3 \end{vmatrix}$$

• Also note that $\vec{N}_i \cdot \vec{N}_j = (\lambda_{i1} \nabla \lambda_{i2} - \lambda_{i2} \nabla \lambda_{i1}) \cdot (\lambda_{j1} \nabla \lambda_{j2} - \lambda_{j2} \nabla \lambda_{j1})$

•
$$\vec{N}_i \cdot \vec{N}_j = (\lambda_{i1} \nabla \lambda_{i2} - \lambda_{i2} \nabla \lambda_{i1}) \cdot (\lambda_{j1} \nabla \lambda_{j2} - \lambda_{j2} \nabla \lambda_{j1})$$

$$\bullet = \lambda_{i1}\lambda_{j1}\nabla\lambda_{i2}\cdot\nabla\lambda_{j2} - \lambda_{i1}\lambda_{j2}\nabla\lambda_{i2}\cdot\nabla\lambda_{j1} - \lambda_{i2}\lambda_{j1}\nabla\lambda_{i1}\cdot$$

$$\nabla \lambda_{j2} + \lambda_{i2} \lambda_{j2} \nabla \lambda_{i1} \cdot \nabla \lambda_{j1}$$

• =
$$\lambda_{i1}\lambda_{j1}\phi_{i2,j2} - \lambda_{i1}\lambda_{j2}\phi_{i2,j1} - \lambda_{i2}\lambda_{j1}\phi_{i1,j2} + \lambda_{i2}\lambda_{j2}\phi_{i1,j1}$$

• Hence,

•
$$T_{ij} = \int \int_{S} \vec{N}_i \cdot \vec{N}_j dS$$

• =
$$\int \int_{S} (\lambda_{i1}\lambda_{j1}\phi_{i2,j2} - \lambda_{i1}\lambda_{j2}\phi_{i2,j1} - \lambda_{i2}\lambda_{j1}\phi_{i1,j2} + \lambda_{i2}\lambda_{j2}\phi_{i1,j1}) dS$$

- Hence, $T_{ij} = \int \int_{S} \vec{N}_{i} \cdot \vec{N}_{j} dS$
- = $\int \int_{S} (\lambda_{i1}\lambda_{j1}\phi_{i2,j2} \lambda_{i1}\lambda_{j2}\phi_{i2,j1} \lambda_{i2}\lambda_{j1}\phi_{i1,j2} + \lambda_{i2}\lambda_{j2}\phi_{i1,j1}) dS$
- = $\phi_{i2,j2} \int \int_{S} \lambda_{i1} \lambda_{j1} dS \phi_{i2,j1} \int \int_{S} \lambda_{i1} \lambda_{j2} dS$
- $-\phi_{i1,j2} \int \int_{S} \lambda_{i2} \lambda_{j1} dS + \phi_{i1,j1} \int \int_{S} \lambda_{i2} \lambda_{j2} dS$
- It has been shown that $M_{ij} = \int \int_S \lambda_i \lambda_j \, dS$
- $T_{ij} = \phi_{i2,j2} M_{i1,j1} \phi_{i2,j1} M_{i1,j2}$
- $\bullet -\phi_{i1,j2}M_{i2,j1} + \phi_{i1,j1}M_{i2,j2}$