

10.5 Wire Antennas and Scatterers

- Since from the EFIE on the surface of the wire,

$$E_z^{scat}(\rho = a) = -E_z^{inc}(\rho = a)$$

$$\frac{1}{j\omega\epsilon_0} \left(\frac{\partial^2}{\partial z^2} + \beta_0^2 \right) \int_{-L/2}^{L/2} I(z') G(z, z') dz' = -E_z^{inc}(\rho = a)$$

- This equation is called the *Hallen's Integro-differential equation*
- In this case, differential is outside the integral

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$$(b) \quad E_z = \frac{1}{j\omega\epsilon_0} \int_{-L/2}^{L/2} \left(\frac{\partial^2}{\partial z^2} + \beta_0^2 \right) I(z') G(z, z') dz'$$

- This electric field is the field due to current $I(z')$
 - [which results because of the impressed or source field] and
 - this field can be written as the scattered field
- Therefore,

$$E_z^{scat} = \frac{1}{j\omega\epsilon_0} \int_{-L/2}^{L/2} \left(\frac{\partial^2}{\partial z^2} + \beta_0^2 \right) I(z') G(z, z') dz'$$

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- Since from EFIE on the surface of the wire,

$$E_z^{scat}(\rho = a) = -E_z^{inc}(\rho = a)$$

$$\frac{1}{j\omega\epsilon_0} \int_{-L/2}^{L/2} \left(\frac{\partial^2}{\partial z'^2} + \beta_0^2 \right) I(z') G(z, z') dz' = -E_z^{inc}(\rho = a)$$

- This equation is the *Pocklington's Integro-differential equation*
- In this case, the differential has moved inside the integral
- Richmond has simplified the above equation as follows:

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- (c) In cylindrical coordinates,

$$r = |\vec{r} - \vec{r}'| = \left| \sqrt{(z - z')^2 + |\vec{\rho} - \vec{\rho}'|^2} \right|$$

$$\because \rho' = a \therefore |\vec{\rho} - \vec{\rho}'| = \rho^2 + a^2 - 2\rho \bullet \vec{\rho}' = \rho^2 + a^2 - 2\rho a \cos(\phi - \phi')$$

$$\Rightarrow r = |\vec{r} - \vec{r}'| = \sqrt{\rho^2 + a^2 - 2\rho a \cos(\phi - \phi') + (z - z')^2}$$

- Problem under analysis has cylindrical symmetry and
 - observation for any values of ϕ won't make any difference
 - we may assume without loss of generality $\phi = 0$
 - hence $\phi - \phi' = \phi'$

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$$A_z = \mu_0 \int_{-L/2}^{L/2} \frac{I(z')}{2\pi} \int_0^{2\pi} \frac{e^{-j\beta_0 r}}{4\pi r} d\phi' dz'$$

- where $r = \sqrt{\rho^2 + a^2 - 2\rho a \cos(\phi') + (z - z')^2}$
- and the inner integration $\int_0^{2\pi} \frac{e^{-j\beta_0 r}}{4\pi r} d\phi'$
 - is also referred to as cylindrical wire kernel

- Thin wire approximation

$$r \cong \sqrt{\rho^2 + (z - z')^2}$$

- If we assume $a \ll \lambda$ and is very small, we have, ϕ'
- Inner integrand is no more dependent on the variable

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- Therefore

$$A_z = \mu_0 \int_{-L/2}^{L/2} \frac{I(z') e^{-j\beta_0 r}}{4\pi r} dz'$$

- Also called as thin wire approximation
 - with the reduced kernel
- For this case, we can write

$$G(z, z') \cong \frac{e^{-j\beta_0 r}}{4\pi r} = G(r)$$

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- Now in the light of this simplification of the magnetic vector potential,
- we can simplify equation 10.29c (see example 10.4) as follows:

$$\frac{1}{j\omega\epsilon_0 4\pi} \int_{-L/2}^{L/2} I_z(z') \frac{e^{-j\beta_0 r}}{r^5} \left[(1 + j\beta_0 r)(2r^2 - 3a^2) + (\beta_0 ar)^2 \right] dz' = -E_z^{inc}(\rho = a)$$

- This form of the Pocklington's integro-differential is more suitable for MoM formulation
 - since it does not involve any differentiation.

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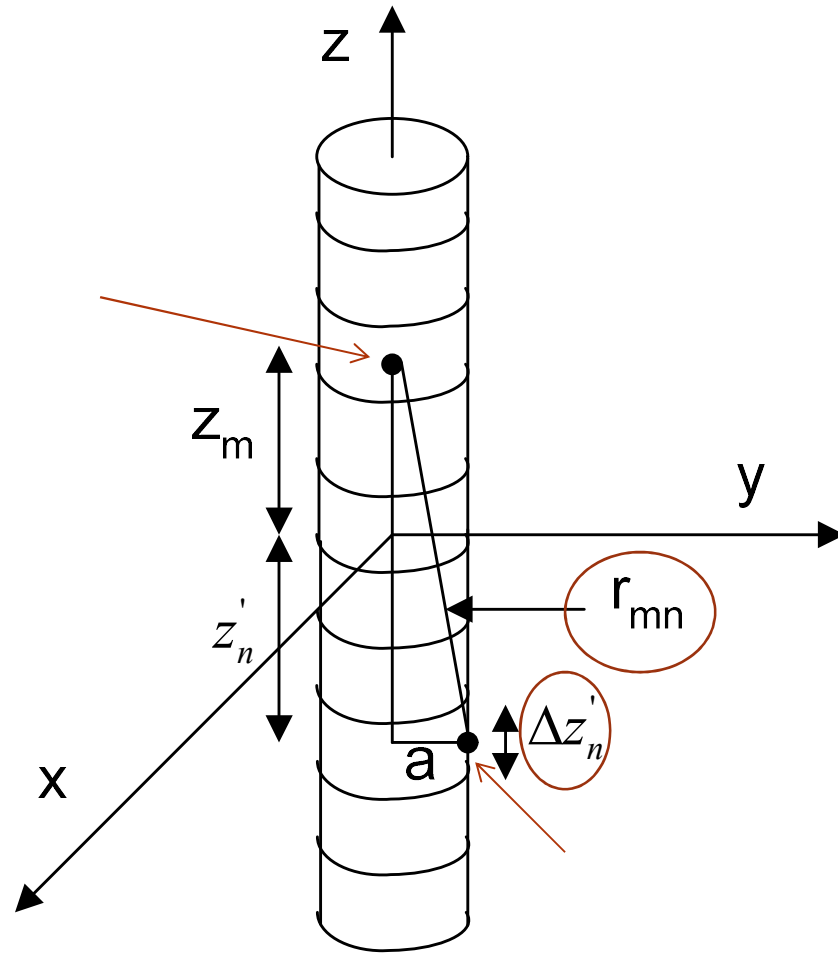
10.5.3 MoM Formulation of Pocklington's Integro-differential equation

- Applying MoM formulation to above integral equation
- Divide the wire in to N segments
- Consider pulse basis function and
 - express the current as a series expansion
 - in the form of a staircase approximation as

$$I(z') = \sum_{n=1}^N I_n b_n(z')$$

where

$$b_n(z') = \begin{cases} 1 & \text{for } \Delta z'_n \\ 0 & \text{otherwise} \end{cases}$$



- Fig. 10.8 Thin wire dipole is divided into N equal segments

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- $\Delta z'_n$ is the length of the n^{th} segment, expressed as

$$-\frac{L}{2} + \frac{L}{N}(n-1) < z \leq -\frac{L}{2} + \frac{L}{N}n$$

$$-E_z^{inc} = \int_{-L/2}^{L/2} I(z') F(z, z') dz'$$

- where $F(z, z') = \frac{1}{j\omega\epsilon} \left(\frac{\partial^2}{\partial z^2} + \beta_0^2 \right) G(z, z')$

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- Substituting $I(z')$ and
 - evaluating at $z=z_m$ (middle of the m^{th} segment) as shown in the Fig. 10.7
- for point matching with weighting functions as $w_m(z) = \delta(z - z_m)$
- where z_m is the center of the segment m

$$z_m = -\frac{L}{2} + \frac{L}{N}(m - 0.5)$$

- and $m=1, 2, 3, \dots, M$, we can write,

$$-E_z^i(z_m) = \sum_{n=1}^N I_n \int_{\Delta z'_n} F(z_m, z') dz'$$

10.5 Wire Antennas and Scatterers

- To overcome the singularity
 - for the self term or diagonal elements of the $[Z]$ matrix
- we have assumed that the source is on the surface of the wire
 - whereas the observation is the axis of the wire
- Using mid-point integration, we have,

$$-E_z^i(z_m) = \sum_{n=1}^N I_n F_{mn}$$

- where $F_{mn} = \int_{\Delta z'_n} F(z_m, z') dz' \cong F(z_m, z'_n) \Delta z'_n$

10.5 Wire Antennas and Scatterers

- For $m=1,2,\dots,M$,

$$\begin{bmatrix} F_{11} & F_{12} & \dots & F_{1N} \\ F_{21} & F_{22} & \dots & F_{2N} \\ \vdots & \vdots & \vdots & \vdots \\ F_{M1} & F_{M2} & \dots & F_{MN} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ \vdots \\ I_N \end{bmatrix} = \begin{bmatrix} -E_z^{inc}(z_1) \\ -E_z^{inc}(z_2) \\ \vdots \\ -E_z^{inc}(z_N) \end{bmatrix}$$

- In the compact form, we can write

$$[F_{mn}][I_n] = -[E_m]$$

- Multiplying both sides by Δz , we can write,

$$[Z_{mn}][I_n] = -[V_m]$$

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- $[I_n]$ can be computed by matrix inversion
 - Can find the approximate current distribution on the antenna
- Other important antenna parameters are
 - input impedance of the antenna and
 - the total radiated fields
- which can be obtained as:

$$Z_{input} = \frac{2V_0}{I_{\frac{N}{2}}}$$

$$\vec{E}^{tot}(\vec{r}) = \vec{E}^{inc}(\vec{r}) + \vec{E}^{scat}(\vec{r}) = \vec{E}^{inc}(\vec{r}) + \int_{-L/2}^{L/2} \sum_{n=1}^N I_n b_n(z') \frac{1}{j\omega\epsilon 4\pi} \left(\frac{\partial^2}{\partial z'^2} + \beta_0^2 \right) \frac{e^{-j\beta_0 r}}{r} dz'$$

10.5 Wire Antennas and Scatterers

Example 10.5

- Consider a short dipole (thin wire antenna) of length 0.3λ and radius 0.01λ .
- Find the current distribution on the short dipole and input impedance using MoM.
- Assume frequency of operation of the antenna is at 1 MHz.
- Choose the number of discretizations on the thin wire as three segments only.

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- For three segments discretization ($\Delta z = 0.1\lambda$) on the thin wire antenna
- the MoM matrix equation will be

$$\begin{bmatrix} Z_{11} & Z_{12} & Z_{13} \\ Z_{21} & Z_{22} & Z_{23} \\ Z_{31} & Z_{32} & Z_{33} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = - \begin{bmatrix} V_1 \\ V_2 \\ V_3 \end{bmatrix}$$
$$\Rightarrow \Delta z \begin{bmatrix} F_{11} & F_{12} & F_{13} \\ F_{21} & F_{22} & F_{23} \\ F_{31} & F_{32} & F_{33} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = -\Delta z \begin{bmatrix} E_1 \\ E_2 \\ E_3 \end{bmatrix}$$

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- where

$$Z_{mn} = F_{mn} \Delta z = \frac{e^{-j\beta_0 r_{mn}} \left[(1 + j\beta_0 r_{mn})(2r_{mn}^2 - 3a^2) + (\beta_0 a r_{mn})^2 \right] \Delta z}{j\omega\epsilon_0 4\pi r_{mn}^5}$$

- Simplifying the above expression of the Z_{mn} (see book)

$$Z_{mn} = \frac{-jZ_0 \frac{\Delta z}{\lambda} \left[\left(1 + j2\pi \frac{r_{mn}}{\lambda} \right) \left(2 - 3 \left(\frac{a}{r_{mn}} \right)^2 \right) + \left(2\pi \frac{a}{\lambda} \right)^2 \right] \left\{ \cos \left(2\pi \frac{r_{mn}}{\lambda} \right) - j \sin \left(2\pi \frac{r_{mn}}{\lambda} \right) \right\}}{8\pi^2 \lambda \left(\frac{r_{mn}}{\lambda} \right)^3}$$

10.5 Wire Antennas and Scatterers

- For thin wire approximations,

$$r_{mn} \cong \sqrt{\rho^2 + (z_m - z_n)^2}$$

$$\therefore r_{11} = \sqrt{a^2} = a = r_{22} = r_{33} = 0.01\lambda;$$

$$r_{12} = \sqrt{a^2 + \Delta z^2} = r_{21} = r_{23} = r_{32} = 0.1\lambda;$$

$$r_{13} = \sqrt{a^2 + (2\Delta z)^2} = r_{31} = 0.2\lambda$$

- [Z] symmetric Toeplitz matrix (need to calculate the first row of the matrix only)

$$[Z] = \begin{bmatrix} Z_1 & Z_2 & Z_3 \\ Z_2 & Z_1 & Z_3 \\ Z_3 & Z_2 & Z_1 \end{bmatrix}$$

10.5 Wire Antennas and Scatterers

- About the $[V]$ matrix, for delta gap excitation,

$$[V] = - \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

- since a voltage $1V$ exists at the feed gap only
- Solve the $[I]$ matrix and get the current distribution
- and the input impedance can be calculated as

$$Z_{input} = \frac{2V_0}{I_{\frac{N}{2}}} = \frac{1}{I_2}$$

10.6 Software language for implementation of electromagnetics codes

- *Choice of software languages* for implementing electromagnetics code
- FORTRAN language complex numbers are a built-in datatype
- Many computational electromagnetics programmer prefer
 - to use FORTRAN language
 - for implementing their algorithms
- Earlier versions of FORTRAN were a functional language

10.6 Software language for implementation of electromagnetics codes

- New versions of FORTRAN are object-oriented languages
- C++, another object-oriented language,
 - is also widely used for many numerical methods
- FORTRAN and C++ are efficient in implementation
 - since the computational time is less
- MATLAB is also convenient environments since
 - it accepts complex numbers,
 - graphics are very easy to create and
 - many in-built functions are readily available for use

10.6 Software language for implementation of electromagnetics codes

- MATLAB any additional “for” loop in the program,
 - the time it takes to run the program increases drastically
- Good to consider the advantages and disadvantages
 - for employment of any software language
- For instance,
 - drawing graphics in C is somewhat involved,
 - but MATLAB is convenient for such things.
 - program written in C runs faster than MATLAB and so on

10.6 Software language for implementation of electromagnetics codes

- Computational electromagnetics is a topic
 - which you can learn only by doing
- Some simulation exercises are given at the end of the chapter,
- you should always write down a
 - MATLAB or
 - any other software language program
- in which you are comfortable and
- see those results

10.7 Summary

- Summarize the three steps involved in MoM:
 - (a) *Derivation of appropriate integral equations*
 - (b) *Conversion or discretization of the integral equation into*
 - *a matrix equation using*
 - *basis or expansion functions and*
 - *weighting or testing functions*
 - *as well as evaluation of the matrix elements*
 - (c) *Solving the matrix equation and*
 - *obtaining the desired parameters*

Dipole (Electrostatics)

- Programming Exercise 1 (In-class)
- Assume feed at the centre
- Radius of cylindrical dipole, $a = 0.00065$ m
- Length of dipole, $2l = 0.005$ m
- Permittivity of free space, $\epsilon_0 = 8.8541878176 \times 10^{-12}$ F/m
- Relative permittivity, $\epsilon_r = 1$ (air)
- Number of segments (pulses), $N = 30$
- Segment length, $\Delta z = 2l/N$
- Match point, z_m at segment m
- $z_m = (m - 0.5)\Delta z$ $m = 1, 2, 3, \dots, N$

Dipole (Electrostatics)

- Discretization of Z_{mn}

$$Z_{mn} = \begin{cases} 2 \ln \left(\frac{(\Delta z/2) + \sqrt{a^2 + (\Delta z/2)^2}}{a} \right) & m = n \\ \ln \left(\frac{z_m + (\Delta z/2) - z_n + \sqrt{a^2 + (z_m - z_n + \Delta z/2)^2}}{z_m - (\Delta z/2) - z_n + \sqrt{a^2 + (z_m - z_n - \Delta z/2)^2}} \right) & m \neq n \end{cases}$$

- To create a complete matrix, $[Z_{mn}]$:

$$\begin{bmatrix} Z_{11} & Z_{12} & \cdots & Z_{1,30} \\ Z_{21} & Z_{22} & \cdots & Z_{2,30} \\ \vdots & \vdots & \ddots & \vdots \\ Z_{30,1} & Z_{30,2} & \cdots & Z_{30,30} \end{bmatrix}$$

Dipole (Electrostatics)

- Discretization voltage, V
- $V_o = 1$
- $V_m = 4\pi\epsilon_o\epsilon_r V_o$
- To create transpose matrix, $[V_m]$:

$$\begin{bmatrix} V_1 \\ V_2 \\ V_3 \\ \vdots \\ V_{30} \end{bmatrix}$$

Dipole (Electrostatics)

- The unknown charge densities, $[I_n]$ along the dipole are determined
 - by inverting the matrix, $[Z_{mn}]$ and multiplying with the voltage, $[V_m]$

$$\begin{bmatrix} I_1 \\ I_2 \\ \vdots \\ I_{30} \end{bmatrix} = \begin{bmatrix} Z_{11} & Z_{12} & \cdots & Z_{1,30} \\ Z_{21} & Z_{22} & \cdots & Z_{2,30} \\ \vdots & \vdots & \ddots & \vdots \\ Z_{30,1} & Z_{30,2} & \cdots & Z_{30,30} \end{bmatrix}^{-1} \begin{bmatrix} V_1 \\ V_2 \\ \vdots \\ V_{30} \end{bmatrix}$$

- Write a MATLAB program to plot line charge density (pC) versus distance (mm) of the centre-fed dipole

Programming Exercise 3 (Homework)

- Write a MATLAB program to find the current distribution and input impedance of a centre-fed dipole
- Hints:
 - Pocklington's equation (Richmond's expression)

$$\frac{1}{j\omega\epsilon_0 4\pi} \int_{-L/2}^{L/2} I_z(z') \frac{e^{-jkr}}{r^5} \left[(1+jkr)(2r^2-3a^2) + (kar)^2 \right] dz' = -E_z^{inc}(\rho=a)$$

- Piece-wise constant function
- Magnetic frill source
- Point-matching method

Dipole (Pocklington's Equation)

Electrodynamic case

- Define z coordinate as symbol
- Radius cylindrical dipole, $a = 0.00065$ m
- Outer radius coaxial line, $b = 0.00205$ m
- Half length dipole, $h = 0.005$ m
- Operation frequency, $f = 1$ GHz
- Light velocity, $c = 3 \times 10^8$ m/s

Dipole (Pocklington's Equation)

- Permittivity of free space, $\epsilon_0 = 8.8541878176 \times 10^{-12}$ F/m
- Relative permittivity, $\epsilon_r = 1$ (air)
- Relative permittivity of coaxial line medium, $\epsilon_r = 2.06$ (Teflon)
- Angular frequency, $\omega = 2\pi f$
- Propagation constant, $k = 2\pi f (\epsilon_r)^{0.5} / c$

Dipole (Pocklington's Equation)

- Number segment (pulses), $N = 9$ (odd number)
- Segment length, $\Delta z = 2h/N$
- Match point, z_m at segment m
- $z_m = (m - 0.5)\Delta z - h \quad m = 1, 2, 3, \dots, N$

Dipole (Pocklington's Equation)

- Discretization of Z_{mn}

$$Z_{mn} = \frac{1}{4\pi} \times \int_{z_n - \Delta z/2}^{z_n + \Delta z/2} \frac{e^{-jkr_m}}{r_m^5} \left[\begin{array}{l} (1 + jkr_m)(2r_m^2 - 3a^2) \\ + (kar_m)^2 \end{array} \right] dz'$$

- where

$$r_m = \sqrt{a^2 + (z_m - z')^2}$$

Dipole (Pocklington's Equation)

- The integral Z_{mn} can be solved by numerical integration (*quadv* function in MATLAB toolbox) for point z_1 at $m = 1$ segment
- We assume that $z_m = z_n$ and solve the integral from $z_n - (\Delta z/2)$ to $z_n + (\Delta z/2)$ and yield the matrix
- $[Z_{11}, Z_{12}, Z_{13}, Z_{14}, Z_{15}, Z_{16}, Z_{17}, Z_{18}, Z_{19}]$

Dipole (Pocklington's Equation)

- To create a matrix:

$$\begin{bmatrix} Z_{11}/2 & Z_{12} & Z_{13} & Z_{14} & \cdots & Z_{19} \\ 0 & Z_{11}/2 & Z_{12} & Z_{13} & \cdots & Z_{18} \\ 0 & 0 & Z_{11}/2 & Z_{12} & \cdots & Z_{17} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & Z_{11}/2 \end{bmatrix}$$

Dipole (Pocklington's Equation)

- To create a complete matrix, $[Z_{mn}]$:

$$\begin{bmatrix} Z_{11} & Z_{12} & Z_{13} & Z_{14} & \cdots & Z_{19} \\ Z_{12} & Z_{11} & Z_{12} & Z_{13} & \cdots & Z_{18} \\ Z_{13} & Z_{12} & Z_{11} & Z_{12} & \cdots & Z_{17} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ Z_{19} & Z_{18} & Z_{17} & Z_{16} & \cdots & Z_{11} \end{bmatrix}$$

- Magnetic frill source⁺
- the feed gap is replaced with a circumferentially directed magnetic current density existing over an annular aperture

⁺<https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=5948354>

Dipole (Pocklington's Equation)

- The inner radius of the aperture is that of the wire and outer radius is found from the characteristic impedance of the transmission line feeding the antenna
- For this frill source the electric field is found on the surface of the wire
- Discretization electric field, E_z

$$E_{z_m}^i = \frac{-j\omega\epsilon_0 V_o}{\ln(b/a)} \left[\frac{e^{-jkr_1}}{r_1} - \frac{e^{-jkr_2}}{r_2} \right]$$

- where $r_1 = \sqrt{z_m^2 + a^2}$ $r_2 = \sqrt{z_m^2 + b^2}$

Dipole (Pocklington's Equation)

- assume $V_0=1$.
- To create transpose matrix, $[E_m]$:

$$\begin{bmatrix} E_{z1}^i \\ E_{z2}^i \\ E_{z3}^i \\ \vdots \\ E_{z9}^i \end{bmatrix}$$

- The unknown current vector, $[I_n]$ along the dipole is determined by
 - inverting the matrix, $[Z_{mn}]$ and multiplying with the electric field vector, $[E_m]$

Dipole (Pocklington's Equation)

$$\begin{bmatrix} I_1 \\ I_2 \\ I_3 \\ \vdots \\ I_9 \end{bmatrix} = \begin{bmatrix} Z_{11} & Z_{12} & Z_{13} & Z_{14} & \cdots & Z_{19} \\ Z_{12} & Z_{11} & Z_{12} & Z_{13} & \cdots & Z_{18} \\ Z_{13} & Z_{12} & Z_{11} & Z_{12} & \cdots & Z_{17} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ Z_{19} & Z_{18} & Z_{17} & Z_{16} & \cdots & Z_{11} \end{bmatrix}^{-1} \begin{bmatrix} E_{z1}^i \\ E_{z2}^i \\ E_{z3}^i \\ \vdots \\ E_{z9}^i \end{bmatrix}$$

- The input impedance, Z_{in} at coaxial fed point (at $z_5 = 0$).
- We assume $v_0 = 1$ V.
- $Z_{in} = v_0 / I_5$