Physics II (PH 102) Electromagnetism (Lecture 7)

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Concept of Electric Flux

Definition

Let S be any arbitrary simple surface (open or closed) and E is the Electric field in the region containing S . Then, the total flux of E through the surface is defined as the surface integral of the outward normal component of E on S :

$$
\phi_S = \iint\limits_{S} \mathbf{E} \cdot d\mathbf{A} = \iint\limits_{S} E \, dA \cos \phi = \frac{q}{4\pi\epsilon_0} \iint\limits_{S} \left(\frac{dA \cos \phi}{r^2} \right) = \frac{q}{4\pi\epsilon_0} \int\limits_{\text{Solid angle}} d\Omega = \frac{q}{\epsilon_0}
$$

Thus, the result is independent of the specific geometry of the surface S .

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Electric Flux due to Point Charge

Example

Consider a charge q placed at the origin. Find the Electric flux through the upper hemispherical surface of radius R centered at the origin.

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Let $d{\sf A}=R^2\sin\theta d\theta d\phi$ $\hat{\sf r}$ be an elementary area on the hemesphere at ${\sf r}=R\,\hat{\sf r}$, where $|r| = R$, and unit normal to dA is \hat{r} . Hence, the Electric flux is

$$
\phi_{S} = \iint_{S} \mathbf{E}(\mathbf{r}) \cdot d\mathbf{A} ; \quad \mathbf{E}(\mathbf{r} = R\,\hat{\mathbf{r}}) = \frac{q}{4\pi\epsilon_{0}} \left(\frac{\hat{\mathbf{r}}}{R^{2}}\right)
$$

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$$

$$
= \frac{q}{4\pi\epsilon_0} \int_0^{\pi/2} \int_0^{2\pi} \left(\frac{\hat{\mathbf{r}}}{R^2}\right) \cdot \hat{\mathbf{r}} R^2 \sin\theta d\theta d\phi
$$

$$
= \frac{q}{2\epsilon_0}
$$

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Let E be the Electric field defined over a volume V with volume charge density ρ , then using the differential form of Gauss's law we have

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\nabla \cdot \mathbf{E}(\mathbf{r}) = \frac{\rho(\mathbf{r})}{\epsilon_0}
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$$

$$
\iiint\limits_{V} \nabla \cdot \mathbf{E}(\mathbf{r}) dV = \iiint\limits_{V} \frac{\rho(\mathbf{r})}{\epsilon_0} dV = \frac{Q_{\text{enclosed}}}{\epsilon_0}
$$

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where $Q_{\rm enclosed}$ is the total charge enclosed within V .

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$$
\iiint_V \nabla \cdot \mathbf{E}(\mathbf{r}) d\nu = \iiint_V \frac{\rho(\mathbf{r})}{\epsilon_0} d\nu = \frac{Q_{enclosed}}{\epsilon_0}
$$

where Q_{enclosed} is the total charge enclosed within V . If V be bounded by a closed surface S , then according to the Gauss's Divergence Theorem

$$
\iiint\limits_V \nabla \cdot \mathbf{E}(\mathbf{r}) d\mathbf{v} = \frac{Q_{\text{enclosed}}}{\epsilon_0} = \oiint\limits_S \mathbf{E}(\mathbf{r}) \cdot d\mathbf{A} = \phi_S
$$

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$$

Gauss's Integral Law:

The surface integral of the outward normal component of the Electric field, i.e., the total normal Electric flux, ϕ_S over a closed surface S enclosing a total charge Q_{enclosed} is equal the ratio $Q_{\text{enclosed}}/\epsilon_0$, and this result is independent of the specific geometry (shape) of the surface. Mathematically,

$$
\phi_S = \oiint_S \mathbf{E}(\mathbf{r}) \cdot d\mathbf{A} = \frac{Q_{enclosed}}{\epsilon_0}
$$

Gauss's Integral Law can ONLY be applied to problems with HIGH DEGREE OF SYMMETRY where one can construct GAUSSIAN SURFACES.

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- First contruct a fully closed GAUSSIAN SURFACE. Open surfaces, like discs, can not enclose charge in a 3D volume.
- \blacktriangleright The surface must include the point where the Electric field is calculated.
- ▶ The surface is chosen in such a way that for every point on that surface the Electric field E is constant.

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- \triangleright 4 types of symmetries can be exploited: (1) Spherical, (2) Cylindrical (3) Cubical and (4) Planar. Accordingly, the Gaussian surfaces are constructed spherical, cylindrical, cubical and pillbox shaped.

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- \triangleright 4 types of symmetries can be exploited: (1) Spherical, (2) Cylindrical (3) Cubical and (4) Planar. Accordingly, the Gaussian surfaces are constructed spherical, cylindrical, cubical and pillbox shaped.
- \triangleright Surface integration drastically simplifies, since E being constant can be taken outside the integral.

$$
\phi_s = \oiint\limits_{S} \mathbf{E} \cdot d\mathbf{A} = \mathbf{E} \cdot \hat{n} \oiint\limits_{S} dA = E_n(\text{Surface Area})
$$

Typical Gaussian Surfaces

Applications of Gauss's Law

Example

Consider a uniformly charged insulating sphere of radius R and charge Q. Calculate Electric fields both outside and inside the sphere.

Outside the charged Sphere $(r > R)$

Construct a Gaussian surface S_{out} of raduis r outside the charged sphere with the same center, then the total enclosed charge is Q . Thus,

$$
\oiint_{S_{\text{out}}} \mathbf{E} \cdot d\mathbf{A} = |\mathbf{E}| \oiint_{S_{\text{out}}} \hat{\mathbf{r}} \cdot \hat{\mathbf{r}} dA = |\mathbf{E}| 4\pi r^2 = \frac{Q}{\epsilon_0}
$$
\n
$$
\mathbf{E}(r) = \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2} \hat{\mathbf{r}}.
$$

Inside the charged Sphere $(r < R)$

Construct a Gaussian surface S_{in} of raduis r inside the charged sphere with the same center. The amount of charge enclosed is

$$
q_{\text{enclosed}} = \frac{Q}{\frac{4}{3}\pi R^3} \left(\frac{4}{3}\pi r^3\right) = \frac{Q r^3}{R^3}.
$$

Thus,

$$
\oiint_{S_{\text{in}}} \mathbf{E} \cdot d\mathbf{A} = |\mathbf{E}| \oiint_{S_{\text{in}}} \hat{\mathbf{r}} \cdot \hat{\mathbf{r}} dA = |\mathbf{E}| 4\pi r^2 = \frac{1}{\epsilon_0} \left(\frac{Q r^3}{R^3} \right)
$$

$$
\mathbf{E}(r) = \frac{1}{4\pi \epsilon_0} \frac{Q r}{R^3} \hat{\mathbf{r}}.
$$

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Suppose a Point Source Charge of magnitude q is placed at the origin. Electric field at a Field point r is

$$
\mathsf{E}(\mathsf{r})=\frac{q}{4\pi\epsilon_0}\frac{\mathsf{r}}{r^3}.
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$$

Now curl of Electric field in Cartesian system will be

$$
\nabla \times \mathbf{E}(\mathbf{r}) = \frac{q}{4\pi\epsilon_0} \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \partial_x & \partial_y & \partial_z \\ (x/r^3) & (y/r^3) & (z/r^3) \end{vmatrix}
$$

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$$

$$
[\nabla \times \mathbf{E}(\mathbf{r})]_x = \frac{q}{4\pi\epsilon_0} \left[\partial_y \left(\frac{z}{r^3} \right) - \partial_z \left(\frac{y}{r^3} \right) \right]
$$

$$
= \frac{q}{4\pi\epsilon_0} \left[\left(-\frac{3yz}{r^5} \right) - \left(\frac{-3zy}{r^5} \right) \right] = 0.
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= \frac{q}{4\pi\epsilon_0} \left[\left(-\frac{3yz}{r^5} \right) - \left(\frac{-3zy}{r^5} \right) \right] = 0.
$$

Similarly, the other components: $\left[\nabla \times {\sf E}({\sf r}) \right]_{\sf y} = \left[\nabla \times {\sf E}({\sf r}) \right]_{\sf z} = 0$. Thus,

$$
\nabla \times \mathsf{E}(\mathsf{r})=0
$$

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This is a general result in ELECTROSTATICS, but not necesarily in ELECTRODYNAMICS where $\nabla \times \vec{\mathcal{E}}(\mathbf{r},t) \neq 0$

Curl of Electric Field due to a Continuous Volume Distribution

Now we extend the result to arbitrary Volume Charge Distribution V with volume density ρ . Electric field at the target point P is given by

$$
\mathsf{E}(\mathsf{r}) = \frac{1}{4\pi\epsilon_0} \iiint\limits_{V} \frac{\rho(\mathsf{r}') \left(\mathsf{r} - \mathsf{r}'\right)}{\left|\mathsf{r} - \mathsf{r}'\right|^3} d\mathsf{v}'
$$

Curl with respect to which variable, **r** or **r'**, i.e., is it $\nabla \times$ or $\nabla' \times$?

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Curl with respect to which variable, **r** or **r'**, i.e., is it $\nabla \times$ or $\nabla' \times$? Here we are interested in the curl with respect to TARGET POINT variable r:

$$
\nabla \times \mathsf{E}(\mathsf{r}) = \frac{1}{4\pi\epsilon_0} \nabla \times \iiint\limits_V \frac{\rho(\mathsf{r}') \left(\mathsf{r} - \mathsf{r}'\right)}{|\mathsf{r} - \mathsf{r}'|^3} d\nu'
$$

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$$

$$
= \frac{1}{4\pi\epsilon_0} \iiint\limits_V \rho(\mathbf{r}') \left(\nabla \times \frac{(\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3}\right) d\nu'
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$$

$$
= \frac{1}{4\pi\epsilon_0} \iiint_V \rho(\mathbf{r}') \left(\nabla \times \frac{(\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3}\right) d\nu'
$$

$$
\left(\nabla \times \frac{(\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3}\right)_x = \left(-3(z - z') \frac{(y - y')}{|\mathbf{r} - \mathbf{r}'|^5} + 3(y - y') \frac{(z - z')}{|\mathbf{r} - \mathbf{r}'|^5}\right) = 0
$$

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The other components similarly vanish.

Curl with respect to which variable, **r** or **r'**, i.e., is it $\nabla \times$ or $\nabla' \times$? Here we are interested in the curl with respect to TARGET POINT variable r:

$$
\nabla \times \mathbf{E}(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \nabla \times \iiint_{V} \frac{\rho(\mathbf{r}') (\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3} d\nu'
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= \frac{1}{4\pi\epsilon_0} \iiint_{V} \rho(\mathbf{r}') (\nabla \times \frac{(\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3}) d\nu'
$$

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$$

The other components similarly vanish.

Curl of Electric field E is ALWAYS zero in electrostatics, and therefore E can be derived from the gradient of an arbitrary scalar field $\phi(\mathbf{r})$:

 $\nabla \times \mathbf{E}(\mathbf{r}) = 0 \implies \mathbf{E}(\mathbf{r}) = \nabla \phi(\mathbf{r})$

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Note: In electrodynamics, for time varying e.m. fields, $\nabla \times \vec{\mathcal{E}}(\mathbf{r},t) \neq 0$.

Electric field ${\sf E}$ is by convention taken as the negative gradient of the Electrostatic Potential V .

$$
E(r) = -\nabla V(r)
$$

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Electric field ${\sf E}$ is by convention taken as the negative gradient of the Electrostatic Potential V .

$$
\begin{array}{rcl} \mathsf{E}(\mathsf{r}) & = & -\nabla V(\mathsf{r}) \\ \mathsf{E}(\mathsf{r}) \cdot d\mathsf{r} & = & -dV(\mathsf{r}) \end{array}
$$

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$$

Integrating from a reference point ref to the point r along arb. path C :

$$
\int\limits_{C} \mathbf{E}(\mathbf{r}') \cdot d\mathbf{r}' = -\int\limits_{\text{ref}}^{\mathbf{r}} \nabla V(\mathbf{r}') \cdot d\mathbf{r}' = -\int\limits_{\text{ref}}^{\mathbf{r}} dV = -V(\mathbf{r}) + \underline{\mathcal{Y}}(\text{ref})^{\neq 0}
$$

The ref point is so chosen that the Potential at that location is zero, which is conventionally taken at ref $=\infty$ for finite charge distributions and for infinitely extended charge distributions the ref point may be chosen arbitrarily.

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Definition

The Electrostatic Potential at any point in an existing electric field is equal to the work done by an external agent against the repulsive electric forces in carrying a unit positive test charge from infinity to that point, i.e.,

$$
V(\mathbf{r}) = -\int_{\infty}^{\mathbf{r}} \mathbf{E}(\mathbf{r}') \cdot d\mathbf{r}'
$$

 \blacktriangleright SI Unit: Joules per Coulomb (J/C) or volt (V).

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- \blacktriangleright SI Unit: Joules per Coulomb (J/C) or volt (V).
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- \triangleright Sign Convension: A positive Potential implies work done by the external agent on the Electrostatic field, and a negative Potential implies work done by the Electrostatic field.
- \triangleright Corollary from Stokes' Theorem: Since $\nabla \times \mathsf{E}(\mathsf{r}) = 0$, the circulation of the Electric field about any closed path is zero, and so is the net work done \implies conservative nature of Electric field.

$$
\iint\limits_{S} \left[\nabla \times \mathbf{E}(\mathbf{r}) \right] \cdot d\mathbf{S} = \oint\limits_{L} \mathbf{E}(\mathbf{r}) \cdot d\mathbf{r} = 0.
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▶ Corollary from Fundamental Gradient Theorem: The line integral of the Electric field is path-independent and depends only on the end points \implies potential difference between the given end points is uniquely given by

$$
\int_{r=a}^{r=b} \mathbf{E}(r) \cdot dr = - \int_{a}^{b} \nabla V(r) \cdot dr = - \int_{a}^{b} dV = V(a) - V(b) \equiv \Delta V_{ab}.
$$

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Electrostatic Potential: Facts (contd.)

 \triangleright Linear Superposition Principle holds for Potentials: The total Electrostatic Potential at any point is the sum of the Electrostatic Potentials due to all the source charges/charge distributions separately, i.e.,

$$
V_{\text{Total}} = V_1 + V_2 + \cdots = \sum_i V_i
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Electrostatic Potential: Facts (contd.)

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▶ General Charge Distribution: For a localized charge distribution with volume, surface and linear densities, ρ , σ , λ , respectively, as well as discrete point charges q_i , the resulting Electrostatic Potential is the Superposition of Potentials due to the independent distributions:

$$
V(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \sum_{i=1}^n \frac{q_i}{|\mathbf{r} - \mathbf{r}'_i|} + \frac{1}{4\pi\epsilon_0} \int_C \frac{\lambda(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} d\mathbf{l}' + \frac{1}{4\pi\epsilon_0} \iint_S \frac{\sigma(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} dS' + \frac{1}{4\pi\epsilon_0} \iiint_V \frac{\rho(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} d\mathbf{v}'.
$$

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Poisson's and Laplace's Equations

▶ We have seen that $\mathsf{E}(\mathsf{r}) = -\nabla V(\mathsf{r})$ and $\nabla \cdot \mathsf{E}(\mathsf{r}) = \frac{\rho(\mathsf{r})}{\epsilon_0}$.

▶ Combining the two yields the POISSON'S EQUATION:

$$
\nabla \cdot \mathbf{E}(\mathbf{r}) = \nabla \cdot [-\nabla V(\mathbf{r})] = -\nabla^2 V(\mathbf{r})
$$

$$
\nabla^2 V(\mathbf{r}) = -\frac{\rho(\mathbf{r})}{\epsilon_0}.
$$

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Poisson's and Laplace's Equations

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$$

$$
\nabla^2 V(\mathbf{r}) = -\frac{\rho(\mathbf{r})}{\epsilon_0}.
$$

In regions where there are no charge distributions, $\rho = 0$, we obtain the **LAPLACE'S EQUATION**, $\nabla^2 V(r) = 0$, e.g., in Cartesian System

$$
\nabla^2 V(\mathbf{r}) = \frac{\partial^2 V(x, y, z)}{\partial^2 x} + \frac{\partial^2 V(x, y, z)}{\partial^2 y} + \frac{\partial^2 V(x, y, z)}{\partial^2 z} = 0.
$$

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Poisson's and Laplace's Equations

▶ We have seen that $\mathsf{E}(\mathsf{r}) = -\nabla V(\mathsf{r})$ and $\nabla \cdot \mathsf{E}(\mathsf{r}) = \frac{\rho(\mathsf{r})}{\epsilon_0}$.

▶ Combining the two yields the POISSON'S EQUATION:

$$
\nabla \cdot \mathbf{E}(\mathbf{r}) = \nabla \cdot [-\nabla V(\mathbf{r})] = -\nabla^2 V(\mathbf{r})
$$

$$
\nabla^2 V(\mathbf{r}) = -\frac{\rho(\mathbf{r})}{\epsilon_0}.
$$

In regions where there are no charge distributions, $\rho = 0$, we obtain the **LAPLACE'S EQUATION**, $\nabla^2 V(r) = 0$, e.g., in Cartesian System

$$
\nabla^2 V(\mathbf{r}) = \frac{\partial^2 V(x,y,z)}{\partial^2 x} + \frac{\partial^2 V(x,y,z)}{\partial^2 y} + \frac{\partial^2 V(x,y,z)}{\partial^2 z} = 0.
$$

▶ Boundary Valued Problems:

 $\sqrt{2}$

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To obtain UNIQUE solutions to such 2nd order Partial Differential Equations (PDEs), require specification of Potentials, Electric fields or charge configurations across boundaries or interface between different media, e.g., conductors or dielectrics with different physical properties. These specifications are termed as BOUNDARY CONDITIONS.

Boundary Conditions on E and V

Consider a arbitrarily shaped smooth *interface* with surface charge density σ . Construct a thin wafer-like Gaussian pillbox across the interface of vanishing thickness $\epsilon \to 0$ and infinitesimally small upper and lower "lid" surface areas Δa . The pillbox is contructed arbitrarily close, stradling to the interface so that the surface looks "locally flat" such that E is 'almost' constant on all its surfaces.

Here we shall find the relations between $E_{\rm above}$ & $E_{\rm below}$ and $V_{\rm above}$ & $V_{\rm below}$.

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Boundary Conditions on E

Applying Gauss's law,

\n
$$
\lim_{\epsilon \to 0} \left[\oint_{\text{pilbox}} \mathbf{E} \cdot d\mathbf{S} \right] = \left(\mathbf{E}_{\text{above}} \cdot \hat{\mathbf{n}}_{\perp \text{above}} + \mathbf{E}_{\text{below}} \cdot \hat{\mathbf{n}}_{\perp \text{below}} \right) \Delta a = \frac{1}{\epsilon_0} Q_{\text{encl}} = \frac{1}{\epsilon_0} \sigma \Delta a
$$
\n
$$
\left(\mathbf{E}_{\text{above}} - \mathbf{E}_{\text{below}} \right) \cdot \hat{\mathbf{n}}_{\perp \text{above}} = \frac{\sigma}{\epsilon_0}
$$
\n
$$
E_{\text{above}}^{\perp} - E_{\text{below}}^{\perp} = \frac{\sigma}{\epsilon_0}
$$

Note: There is no contribution from the sides of the pillbox as $\epsilon \to 0$.

Boundary Conditions on E (contd.)

 \triangleright Next consider a thin rectangular closed loop C stradling across the interface of vanishing ends $\epsilon \to 0$ and side lengths *l*. Then, since **E** is a conservative vector field

$$
\lim_{\epsilon \to 0} \left[\oint_C \mathbf{E} \cdot d\mathbf{l} \right] = 0
$$
\n
$$
(\mathbf{E}_{\text{above}} \cdot \hat{\mathbf{n}}_{||} - \mathbf{E}_{\text{below}} \cdot \hat{\mathbf{n}}_{||}) \quad l = (\mathbf{E}_{\text{above}}^{||} - \mathbf{E}_{\text{below}}^{||}) \quad l = 0
$$
\n
$$
\mathbf{E}_{\text{above}}^{||} = \mathbf{E}_{\text{below}}^{||}
$$

Note: The ends give vanishing contributions since $\epsilon \to 0$.

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Boundary Conditions on E (contd.)

 \blacktriangleright The two previous results can be combined as:

$$
E_{\text{above}}^{\perp}(\mathbf{r}) - E_{\text{below}}^{\perp}(\mathbf{r}) = \frac{\sigma(\mathbf{r})}{\epsilon_{0}}
$$

\n
$$
E_{\text{above}}^{\parallel}(\mathbf{r}) = E_{\text{below}}^{\parallel}(\mathbf{r})
$$

\n
$$
\implies E_{\text{above}}(\mathbf{r}) - E_{\text{below}}(\mathbf{r}) = \frac{\sigma(\mathbf{r})}{\epsilon_{0}} \hat{\mathbf{n}}
$$

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where $\hat{\mathbf{n}} \equiv \hat{\mathbf{n}}_{\perp above}$ is the unit normal vector above the interface.

Boundary Conditions on E (contd.)

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 \blacktriangleright The two previous results can be combined as:

$$
E_{\text{above}}^{\perp}(\mathbf{r}) - E_{\text{below}}^{\perp}(\mathbf{r}) = \frac{\sigma(\mathbf{r})}{\epsilon_0}
$$

$$
E_{\text{above}}^{\parallel}(\mathbf{r}) = E_{\text{below}}^{\parallel}(\mathbf{r})
$$

$$
\implies E_{\text{above}}(\mathbf{r}) - E_{\text{below}}(\mathbf{r}) = \frac{\sigma(\mathbf{r})}{\epsilon_0} \hat{\mathbf{n}}
$$

 $\overline{}$ where $\hat{\mathbf{n}} \equiv \hat{\mathbf{n}}_{\perp \text{above}}$ is the unit normal vector <u>above</u> the interface.

 \blacktriangleright Alternatively taking dot products with $\hat{\mathsf{n}}$ the combined result is:

$$
\nabla V_{\text{above}}(\mathbf{r}) \cdot \hat{\mathbf{n}} - \nabla V_{\text{below}}(\mathbf{r}) \cdot \hat{\mathbf{n}} = -\frac{\sigma(\mathbf{r})}{\epsilon_0}.
$$

▶ Introducing Normal directional derivative: $D_{\hat{\mathbf{n}}} V \equiv \frac{\partial V}{\partial n} = \nabla V \cdot \hat{\mathbf{n}}$

$$
\frac{\partial V_{\text{above}}(\mathbf{r})}{\partial n} - \frac{\partial V_{\text{below}}(\mathbf{r})}{\partial n} = -\frac{\sigma(\mathbf{r})}{\epsilon_0}.
$$

Boundary Condition on V

▶ Consider points a and **b** just above and below the interface separated by an infinitesimal amount $\epsilon \to 0$. The potential difference is given by

$$
\lim_{\epsilon \to 0} [V_{\text{above}}(\mathbf{a}) - V_{\text{below}}(\mathbf{b})] = \lim_{a \to b} \left[\int_{a}^{b} \mathbf{E} \cdot d\mathbf{r} \right] = 0
$$
\n\nHowever, the following equation is:

\n

 $\sqrt{2}$ ✍ $V_{\text{above}}=V_{\text{below}}$

Boundary Conditions: Summary

- \triangleright Boundary conditions on **E** and V apply to all types of **smooth** surfaces, flat or curved, or whether they happen to be charged or not
- ▶ Based on 2 basic principles: (1) Gauss's law and (2) Conservative nature of E.

Fact

- 1. The normal component of the Electric field, E_{\perp} is discontinuous by an amount σ/ϵ_0 across any boundary.
- 2. The tangential component of Electric field, E_{\parallel} is continuous across any boundary.
- 3. The Electrostatic potential V is continuous across any boundary.
- 4. The **Normal derivative** of the potential, $\frac{\partial V}{\partial n}$ is discontinuous by an amount σ/ϵ_0 across any boundary.

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