Physics II (PH 102) Electromagnetism (Lecture 7)

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Concept of Electric Flux

Definition

Let S be any arbitrary simple surface (open or closed) and E is the Electric field in the region containing S. Then, the *total flux of* E *through the surface* is defined as the surface integral of the outward normal component of E on S:

$$\phi_{S} = \iint_{S} \mathbf{E} \cdot d\mathbf{A} = \iint_{S} \mathbf{E} \, dA \cos \phi = \frac{q}{4\pi\epsilon_{0}} \iint_{S} \left(\frac{dA\cos \phi}{r^{2}} \right) = \frac{q}{4\pi\epsilon_{0}} \int_{\text{Solid angle}} d\Omega = \frac{q}{\epsilon_{0}}$$

Thus, the result is independent of the specific geometry of the surface S.



Electric Flux due to Point Charge



Example

Consider a charge q placed at the origin. Find the Electric flux through the upper hemispherical surface of radius R centered at the origin.

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Let $d\mathbf{A} = R^2 \sin\theta d\theta d\phi \hat{\mathbf{r}}$ be an elementary area on the hemesphere at $\mathbf{r} = R \hat{\mathbf{r}}$, where $|\mathbf{r}| = R$, and unit normal to dA is $\hat{\mathbf{r}}$. Hence, the Electric flux is

$$\phi_{5} = \iint_{S} \mathbf{E}(\mathbf{r}) \cdot d\mathbf{A} ; \quad \mathbf{E}(\mathbf{r} = R\,\hat{\mathbf{r}}) = \frac{q}{4\pi\epsilon_{0}} \left(\frac{\hat{\mathbf{r}}}{R^{2}}\right)$$

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$$= \frac{q}{4\pi\epsilon_{0}} \int_{0}^{\pi/2} \int_{0}^{2\pi} \left(\frac{\hat{\mathbf{r}}}{R^{2}}\right) \cdot \hat{\mathbf{r}} R^{2} \sin\theta d\theta d\phi$$
$$= \frac{q}{2\epsilon_{0}}$$

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Let **E** be the Electric field defined over a volume V with volume charge density ρ , then using the **differential form of Gauss's law** we have

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where Q_{enclosed} is the total charge enclosed within V.

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Gauss's Integral Law

The surface integral of the outward normal component of the Electric field, i.e., the total normal Electric flux, ϕ_S over a <u>closed surface</u> S enclosing a total charge $Q_{\rm enclosed}$ is equal the ratio $Q_{\rm enclosed}/\epsilon_0$, and this result is independent of the specific geometry (shape) of the surface. Mathematically,

$$\phi_{S} = \bigoplus_{S} \mathbf{E}(\mathbf{r}) \cdot d\mathbf{A} = \frac{Q_{enclosed}}{\epsilon_{0}}$$

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- First contruct a fully closed GAUSSIAN SURFACE. Open surfaces, like discs, can not enclose charge in a 3D volume.
- ▶ The surface must include the point where the Electric field is calculated.
- The surface is chosen in such a way that for every point on that surface the Electric field E is <u>constant</u>.

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- 4 types of symmetries can be exploited: (1) Spherical, (2) Cylindrical (3) Cubical and (4) Planar. Accordingly, the Gaussian surfaces are constructed spherical, cylindrical, cubical and pillbox shaped.

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- 4 types of symmetries can be exploited: (1) Spherical, (2) Cylindrical (3) Cubical and (4) Planar. Accordingly, the Gaussian surfaces are constructed spherical, cylindrical, cubical and pillbox shaped.
- Surface integration drastically simplifies, since E being constant can be taken outside the integral.

$$\phi_s = \oiint_s \mathbf{E} \cdot d\mathbf{A} = \mathbf{E} \cdot \hat{n} \oiint_s dA = E_n(\text{Surface Area})$$

Typical Gaussian Surfaces



Applications of Gauss's Law

Example

Consider a uniformly charged *insulating* sphere of radius R and charge Q. Calculate Electric fields both outside and inside the sphere.



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Outside the charged Sphere (r > R)

Construct a Gaussian surface S_{out} of raduis r outside the charged sphere with the same center, then the total enclosed charge is Q. Thus,

$$\oint_{S_{\text{out}}} \mathbf{E} \cdot d\mathbf{A} = |\mathbf{E}| \oint_{S_{\text{out}}} \hat{\mathbf{r}} \cdot \hat{\mathbf{r}} dA = |\mathbf{E}| 4\pi r^2 = \frac{Q}{\epsilon_0}$$

$$\mathbf{E}(r) = \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2} \hat{\mathbf{r}}.$$

Inside the charged Sphere (r < R)

Construct a Gaussian surface $S_{\rm in}$ of raduis r inside the charged sphere with the same center. The amount of charge enclosed is

$$q_{\rm enclosed} = \frac{Q}{\frac{4}{3}\pi R^3} \left(\frac{4}{3}\pi r^3\right) = \frac{Q\,r^3}{R^3}.$$

Thus,

$$\oint_{S_{in}} \mathbf{E} \cdot d\mathbf{A} = |\mathbf{E}| \oint_{S_{in}} \hat{\mathbf{r}} \cdot \hat{\mathbf{r}} dA = |\mathbf{E}| 4\pi r^2 = \frac{1}{\epsilon_0} \left(\frac{Q r^3}{R^3} \right)$$

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Suppose a Point Source Charge of magnitude q is <u>placed at the origin</u>. Electric field at a Field point r is

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Now curl of Electric field in Cartesian system will be

$$\nabla \times \mathbf{E}(\mathbf{r}) = \frac{q}{4\pi\epsilon_0} \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \partial_x & \partial_y & \partial_z \\ (x/r^3) & (y/r^3) & (z/r^3) \end{vmatrix}$$

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$$[\nabla \times \mathbf{E}(\mathbf{r})]_x = \frac{q}{4\pi\epsilon_0} \left[\partial_y \left(\frac{z}{r^3} \right) - \partial_z \left(\frac{y}{r^3} \right) \right]$$
$$= \frac{q}{4\pi\epsilon_0} \left[\left(-\frac{3yz}{r^5} \right) - \left(\frac{-3zy}{r^5} \right) \right] = 0.$$

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Similarly, the other components: $[\nabla \times \mathbf{E}(\mathbf{r})]_{y} = [\nabla \times \mathbf{E}(\mathbf{r})]_{z} = 0$. Thus,

$$abla imes \mathbf{E}(\mathbf{r}) = 0$$

This is a general result in ELECTROSTATICS, but not necesarily in ELECTRODYNAMICS where $\nabla \times \vec{\mathcal{E}}(\mathbf{r}, t) \neq 0$

Curl of Electric Field due to a Continuous Volume Distribution

Now we extend the result to arbitrary Volume Charge Distribution V with volume density ρ . Electric field at the target point P is given by

$$\mathbf{E}(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \iiint\limits_{V} \frac{\rho(\mathbf{r}^{'}) \ \left(\mathbf{r} - \mathbf{r}^{'}\right)}{\left|\mathbf{r} - \mathbf{r}^{'}\right|^3} d\mathbf{v}^{'}$$



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Here we are interested in the curl with respect to TARGET POINT variable r:

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$$\nabla \times \mathbf{E}(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \nabla \times \iiint_V \frac{\rho(\mathbf{r}') (\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3} d\mathbf{v}'$$

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$$= \frac{1}{4\pi\epsilon_0} \iiint_V \rho(\mathbf{r}') \left(\nabla \times \frac{(\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3} \right) d\mathbf{v}'$$

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$$\left(\nabla \times \frac{(\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3} \right)_{\times} = \left(-3(z - z') \frac{(y - y')}{|\mathbf{r} - \mathbf{r}'|^5} + 3(y - y') \frac{(z - z')}{|\mathbf{r} - \mathbf{r}'|^5} \right) = 0$$

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The other components similarly vanish.

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Curl of Electric field **E** is ALWAYS zero in <u>electrostatics</u>, and therefore **E** can be derived from the gradient of an arbitrary scalar field $\phi(\mathbf{r})$:

$$abla imes \mathbf{E}(\mathbf{r}) = 0 \qquad \Longrightarrow \qquad \mathbf{E}(\mathbf{r}) =
abla \phi(\mathbf{r})$$

Note: In electrodynamics, for time varying e.m. fields, $\nabla \times \vec{\mathcal{E}}(\mathbf{r}, t) \neq 0$.

Electric field **E** is <u>by convention</u> taken as the <u>negative gradient</u> of the Electrostatic Potential V.

$$\mathsf{E}(\mathsf{r}) = -\nabla V(\mathsf{r})$$

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Integrating from a reference point ref to the point r along arb. path C:

$$\int_{C} \mathbf{E}(\mathbf{r}') \cdot d\mathbf{r}' = -\int_{\text{ref}}^{\mathbf{r}} \nabla V(\mathbf{r}') \cdot d\mathbf{r}' = -\int_{\text{ref}}^{\mathbf{r}} dV = -V(\mathbf{r}) + V(\mathbf{ref})^{-0}$$

The **ref** point is so chosen that the Potential at that location is zero, which is conventionally taken at $ref = \infty$ for <u>finite</u> charge distributions and for <u>infinitely</u> extended charge distributions the **ref** point may be chosen arbitrarily.

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Definition

The *Electrostatic Potential* at any point in an existing electric field is equal to the work done by an external agent against the repulsive electric forces in carrying a unit positive test charge from infinity to that point, i.e.,

$$V(\mathbf{r}) = -\int\limits_{\infty} \mathbf{E}(\mathbf{r}') \cdot d\mathbf{r}'$$

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- Corollary from Stokes' Theorem: Since ∇ × E(r) = 0, the circulation of the Electric field about any closed path is zero, and so is the net work done ⇒ conservative nature of Electric field.

$$\iint\limits_{S} \left[\nabla \times \mathbf{E}(\mathbf{r}) \right] \cdot d\mathbf{S} = \oint\limits_{L} \mathbf{E}(\mathbf{r}) \cdot d\mathbf{r} = 0.$$

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 Corollary from Fundamental Gradient Theorem: The line integral of the Electric field is path-independent and depends only on the end points
 potential difference between the given end points is uniquely given by

$$\int_{\mathbf{r}=\mathbf{a}}^{\mathbf{r}=\mathbf{b}} \mathsf{E}(\mathbf{r}) \cdot d\mathbf{r} = -\int_{\mathbf{a}}^{\mathbf{b}} \nabla V(\mathbf{r}) \cdot d\mathbf{r} = -\int_{\mathbf{a}}^{\mathbf{b}} dV = V(\mathbf{a}) - V(\mathbf{b}) \equiv \Delta V_{ab}.$$

Electrostatic Potential: Facts (contd.)

Linear Superposition Principle holds for Potentials: The total Electrostatic Potential at any point is the sum of the Electrostatic Potentials due to all the source charges/charge distributions separately, i.e.,

$$V_{\text{Total}} = V_1 + V_2 + \cdots = \sum_i V_i$$

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General Charge Distribution: For a localized charge distribution with volume, surface and linear densities, ρ, σ, λ, respectively, as well as discrete point charges q_i, the resulting Electrostatic Potential is the Superposition of Potentials due to the independent distributions:

$$V(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \sum_{i=1}^n \frac{q_i}{|\mathbf{r} - \mathbf{r}'_i|} + \frac{1}{4\pi\epsilon_0} \int_C \frac{\lambda(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} dl' + \frac{1}{4\pi\epsilon_0} \iint_S \frac{\sigma(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} dS' + \frac{1}{4\pi\epsilon_0} \iiint_V \frac{\rho(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} dv'.$$

Poisson's and Laplace's Equations

• We have seen that $\mathbf{E}(\mathbf{r}) = -\nabla V(\mathbf{r})$ and $\nabla \cdot \mathbf{E}(\mathbf{r}) = \frac{\rho(\mathbf{r})}{\epsilon_0}$.

Combining the two yields the **POISSON'S EQUATION**:

$$\nabla \cdot \mathbf{E}(\mathbf{r}) = \nabla \cdot [-\nabla V(\mathbf{r})] = -\nabla^2 V(\mathbf{r})$$
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▶ In regions where there are no charge distributions, $\rho = 0$, we obtain the **LAPLACE'S EQUATION**, $\nabla^2 V(\mathbf{r}) = 0$, e.g., in Cartesian System

$$\nabla^2 V(\mathbf{r}) = \frac{\partial^2 V(x, y, z)}{\partial^2 x} + \frac{\partial^2 V(x, y, z)}{\partial^2 y} + \frac{\partial^2 V(x, y, z)}{\partial^2 z} = 0.$$

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$$\nabla^2 V(\mathbf{r}) = -\frac{\rho(\mathbf{r})}{\epsilon_0}.$$

▶ In regions where there are no charge distributions, $\rho = 0$, we obtain the **LAPLACE'S EQUATION**, $\nabla^2 V(\mathbf{r}) = 0$, e.g., in Cartesian System

$$\nabla^2 V(\mathbf{r}) = \frac{\partial^2 V(x, y, z)}{\partial^2 x} + \frac{\partial^2 V(x, y, z)}{\partial^2 y} + \frac{\partial^2 V(x, y, z)}{\partial^2 z} = 0.$$

Boundary Valued Problems:

To obtain UNIQUE solutions to such 2^{nd} order *Partial Differential Equations* (PDEs), require specification of Potentials, Electric fields or charge configurations across *boundaries* or *interface* between different media, e.g., conductors or dielectrics with different physical properties. These specifications are termed as **BOUNDARY CONDITIONS**.

Boundary Conditions on E and V

Consider a arbitrarily shaped smooth *interface* with surface charge density σ . Construct a thin **wafer-like Gaussian pillbox** across the interface of vanishing thickness $\epsilon \to 0$ and infinitesimally small upper and lower "lid" surface areas Δa . The pillbox is contructed arbitrarily close, stradling to the interface so that the surface looks "locally flat" such that <u>**E** is 'almost' constant on all its surfaces</u>.



Here we shall find the relations between $E_{above} \& E_{below}$ and $V_{above} \& V_{below}$.

Boundary Conditions on **E**

Applying Gauss's law,

$$\lim_{\epsilon \to 0} \left[\oiint_{\text{pillbox}} \mathbf{E} \cdot d\mathbf{S} \right] = (\mathbf{E}_{\text{above}} \cdot \hat{\mathbf{n}}_{\perp \text{above}} + \mathbf{E}_{\text{below}} \cdot \hat{\mathbf{n}}_{\perp \text{below}}) \Delta a = \frac{1}{\epsilon_0} Q_{\text{encl}} = \frac{1}{\epsilon_0} \sigma \Delta a$$
$$(\mathbf{E}_{\text{above}} - \mathbf{E}_{\text{below}}) \cdot \hat{\mathbf{n}}_{\perp \text{above}} = \frac{\sigma}{\epsilon_0}$$
$$E_{\text{above}}^{\perp} - E_{\text{below}}^{\perp} = \frac{\sigma}{\epsilon_0}$$

Note: There is no contribution from the sides of the pillbox as $\epsilon \to 0.$



Boundary Conditions on **E** (contd.)

▶ Next consider a thin rectangular closed loop C stradling across the interface of vanishing ends $\epsilon \rightarrow 0$ and side lengths I. Then, since **E** is a conservative vector field

$$\lim_{\epsilon \to 0} \left[\oint_{C} \mathbf{E} \cdot d\mathbf{I} \right] = 0$$

$$\left(\mathbf{E}_{above} \cdot \hat{\mathbf{n}}_{||} - \mathbf{E}_{below} \cdot \hat{\mathbf{n}}_{||} \right) I = (\mathbf{E}_{above}^{||} - \mathbf{E}_{below}^{||})I = 0$$

$$\mathbf{E}_{above}^{||} = \mathbf{E}_{below}^{||}$$

Note: The ends give vanishing contributions since $\epsilon \rightarrow 0$.



Boundary Conditions on **E** (contd.)

The two previous results can be combined as:

$$E_{above}^{\perp}(\mathbf{r}) - E_{below}^{\perp}(\mathbf{r}) = \frac{\sigma(\mathbf{r})}{\epsilon_{0}}$$

$$E_{above}^{||}(\mathbf{r}) = E_{below}^{||}(\mathbf{r})$$

$$\implies E_{above}(\mathbf{r}) - E_{below}(\mathbf{r}) = \frac{\sigma(\mathbf{r})}{\epsilon_{0}}\hat{\mathbf{n}}$$
where $\hat{\mathbf{n}} \equiv \hat{\mathbf{n}}_{\perp above}$ is the unit normal vector above the interface.

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Boundary Conditions on E (contd.)

The two previous results can be combined as:

$$E_{\text{above}}^{\perp}(\mathbf{r}) - E_{\text{below}}^{\perp}(\mathbf{r}) = \frac{\sigma(\mathbf{r})}{\epsilon_0}$$
$$E_{\text{above}}^{||}(\mathbf{r}) = E_{\text{below}}^{||}(\mathbf{r})$$
$$\implies \mathbf{E}_{\text{above}}(\mathbf{r}) - \mathbf{E}_{\text{below}}(\mathbf{r}) = \frac{\sigma(\mathbf{r})}{\epsilon_0}\hat{\mathbf{n}}$$

where $\hat{\textbf{n}}\equiv\hat{\textbf{n}}_{\perp \rm above}$ is the unit normal vector \underline{above} the interface.

Alternatively taking dot products with n the combined result is:

$$abla V_{ ext{above}}(\mathbf{r}) \cdot \hat{\mathbf{n}} -
abla V_{ ext{below}}(\mathbf{r}) \cdot \hat{\mathbf{n}} = -rac{\sigma(\mathbf{r})}{\epsilon_0}.$$

▶ Introducing Normal directional derivative: $D_{\hat{\mathbf{n}}}V \equiv \frac{\partial V}{\partial n} = \nabla V \cdot \hat{\mathbf{n}}$

Boundary Condition on V

• Consider points **a** and **b** just above and below the interface separated by an infinitesimal amount $\epsilon \rightarrow 0$. The potential difference is given by

$$\lim_{\epsilon \to 0} \left[V_{\text{above}}(\mathbf{a}) - V_{\text{below}}(\mathbf{b}) \right] = \lim_{\mathbf{a} \to \mathbf{b}} \left[\int_{\mathbf{a}}^{\mathbf{b}} \mathbf{E} \cdot d\mathbf{r} \right] = 0$$





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Boundary Conditions: Summary

- Boundary conditions on E and V apply to all types of smooth surfaces, flat or curved, or whether they happen to be charged or not
- Based on 2 basic principles: (1) Gauss's law and (2) Conservative nature of E.

Fact

- 1. The normal component of the Electric field, \mathbf{E}_{\perp} is discontinuous by an amount σ/ϵ_0 across any boundary.
- 2. The tangential component of Electric field, ${\bf E}_{||}$ is continuous across any boundary.
- 3. The Electrostatic potential V is continuous across any boundary.
- 4. The **Normal derivative** of the potential, $\frac{\partial V}{\partial n}$ is discontinuous by an amount σ/ϵ_0 across any boundary.

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