

Qzig-I Solutions

1 DDF = 2

Generalized coordinates: (x, s)

$$x_m = x + s \cos \alpha$$

$$y_m = h - s \sin \alpha$$

$$\dot{x}_m = \dot{x} + \dot{s} \cos \alpha \quad \dot{y}_m = -\dot{s} \sin \alpha$$

$$T = \frac{M}{2} \dot{x}^2 + \frac{m}{2} (\dot{x}_m^2 + \dot{y}_m^2) = \frac{M}{2} \dot{x}^2 + \frac{m}{2} (\dot{x}^2 + \dot{s}^2 + 2\dot{x}\dot{s} \cos \alpha)$$

$$V = mg y_m + \frac{k}{2} (s-l)^2 = mg(h - s \sin \alpha) + \frac{k}{2} (s-l)^2$$

$$\text{So } f = \frac{M}{2} \dot{x}^2 + \frac{m}{2} (\dot{x}^2 + \dot{s}^2 + 2\dot{x}\dot{s} \cos \alpha) - mg(h - s \sin \alpha) - \frac{k}{2} (s-l)^2$$

For the E-L equations,

$$\frac{\partial L}{\partial \dot{x}} = (M+m)\ddot{x} + m\ddot{s} \cos \alpha = \text{const}! \quad (1a) \quad (\text{Since } \frac{\partial L}{\partial x} = 0)$$

$$\text{Or, } (M+m)\ddot{x} + m\ddot{s} \cos \alpha = 0 \quad (1b) \Rightarrow \ddot{x} = -\frac{m\ddot{s} \cos \alpha}{(M+m)} \quad (2)$$

$$\frac{\partial L}{\partial \dot{s}} = m(\ddot{s} + \ddot{x} \cos \alpha) \quad \left| \quad \frac{\partial L}{\partial s} = +mg \sin \alpha - k(s-l) \right.$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{s}} \right) - \frac{\partial L}{\partial s} = 0 \Rightarrow m(\ddot{s} + \ddot{x} \cos \alpha) - mg \sin \alpha + k(s-l) = 0 \quad (3)$$

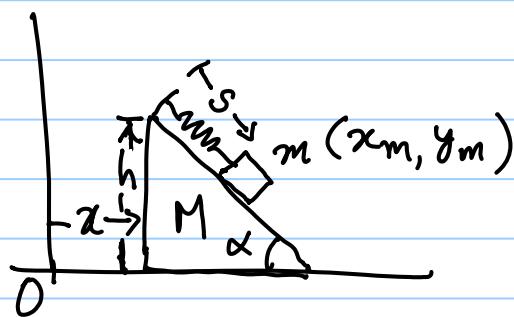
$$\text{Substituting (2) in (3) } \ddot{s} \left(m - \frac{m^2 \cos^2 \alpha}{(M+m)} \right) + ks - kl - mg \sin \alpha = 0 \quad (4)$$

$$\text{Let } q = ks - kl - mg \sin \alpha \quad | \text{ Also } \mu = \frac{m - m^2 \cos^2 \alpha}{(M+m)}$$

$$\ddot{q} = k\ddot{s} \Rightarrow \ddot{s} = \ddot{q}/k$$

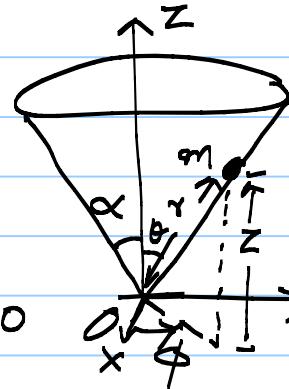
$$(4) \Rightarrow \mu \ddot{q}/k + q = 0 \quad \ddot{q} + (\mu/k) q = 0$$

$$\text{So } \omega = \sqrt{\frac{\mu}{k}} \quad \text{where } \underline{\mu} = \underline{m} \left(1 - \frac{m \cos^2 \alpha}{M+m} \right)$$



2

We shall use spherical polar (r, θ, ϕ) ,
 so that $\underline{\theta = \alpha}$; (r, ϕ) - are the
 generalized coordinates. DOF = 2.



$$\text{velocity of } m, \bar{v} = \dot{r}\hat{r} + r\sin\theta\dot{\phi}\hat{\phi} \quad | \quad \dot{\theta}=0$$

$$S_o \quad T = \frac{m}{2} (\bar{v} \cdot \bar{v}) = \frac{m}{2} \left(\dot{r}^2 + r^2 \sin^2\theta \dot{\phi}^2 \right) \quad | \quad \theta=\alpha$$

$$S_o \quad V = mgz = mg r \cos\alpha$$

$$L = \frac{m}{2} \left(\dot{r}^2 + r^2 \sin^2\alpha \dot{\phi}^2 \right) - mg r \cos\alpha \quad | \quad L \text{ is cyclic in } \phi$$

$$\frac{\partial L}{\partial \dot{r}} = m\ddot{r} \quad | \quad \frac{\partial L}{\partial r} = mr \sin^2\alpha \dot{\phi}^2 - mg \cos\alpha$$

$$S_o \quad F-L \text{ eq. ①} \Rightarrow m\ddot{r} - mr \sin^2\alpha \dot{\phi}^2 + mg \cos\alpha = 0 \quad | \quad ①$$

$$\text{Or, } \ddot{r} - r \sin^2\alpha \dot{\phi}^2 + g \cos\alpha = 0$$

$$p_\phi = \frac{\partial L}{\partial \dot{\phi}} = mr^2 \sin^2\alpha \dot{\phi} = \underline{\underline{\text{conserved}}} \quad | \quad \frac{\partial L}{\partial \phi} = 0 \quad -2$$